

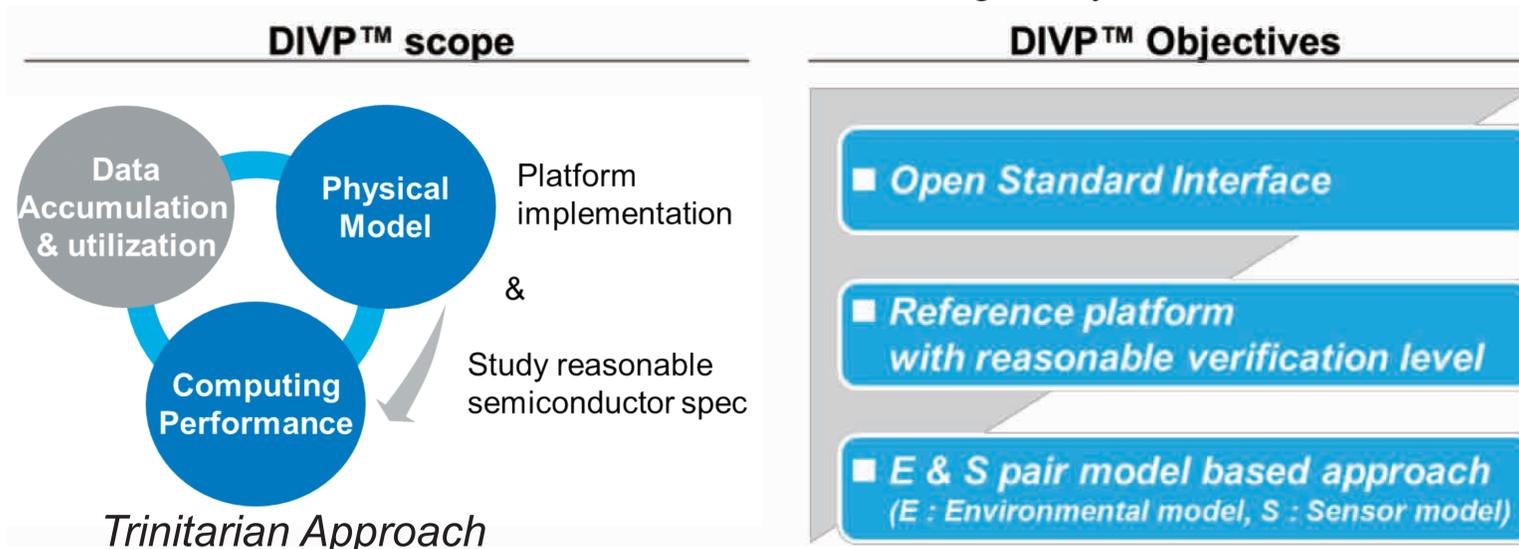


## Validation platform in virtual space for Automated driving system' safety assurance

### DIVP™(Driving Intelligence Validation Platform)

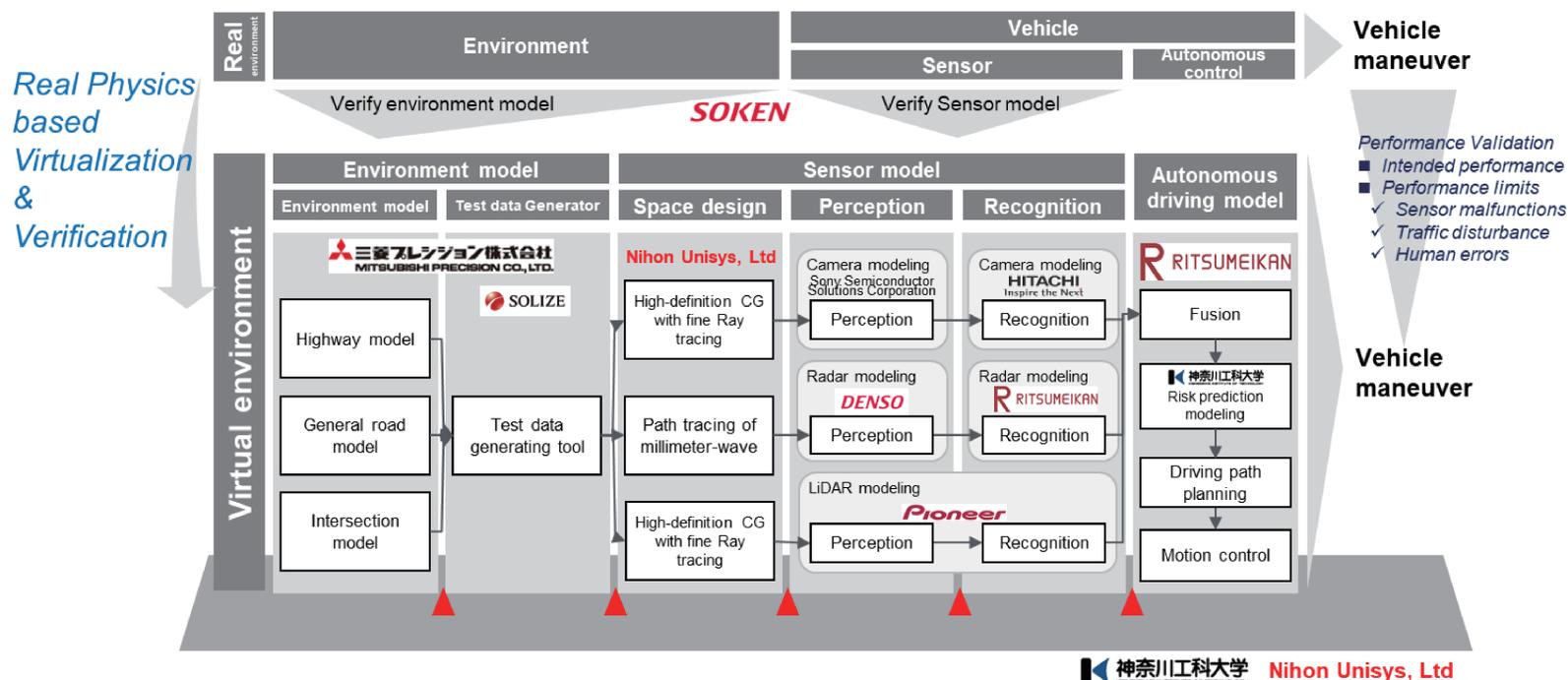
#### Objective & motivation

DIVP™ contributes to enhance the validation of Autonomous Driving Safety assurance



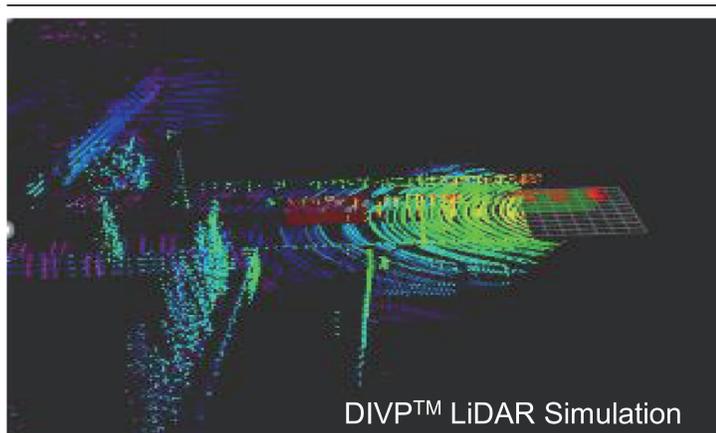
#### Physical modeling

Designed research theme, Duplicate from Real to Virtual, and Verification of correlation level by 10-exparts as DIVP™ Consortium



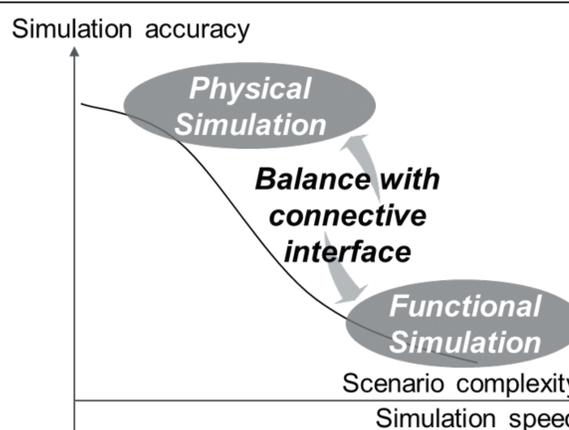
#### Project status

##### Accuracy verification



Duplicates real physics in Simulation and verify the simulation accuracy

##### Usability study



Study the usability by balancing Accurate & Real-time simulations