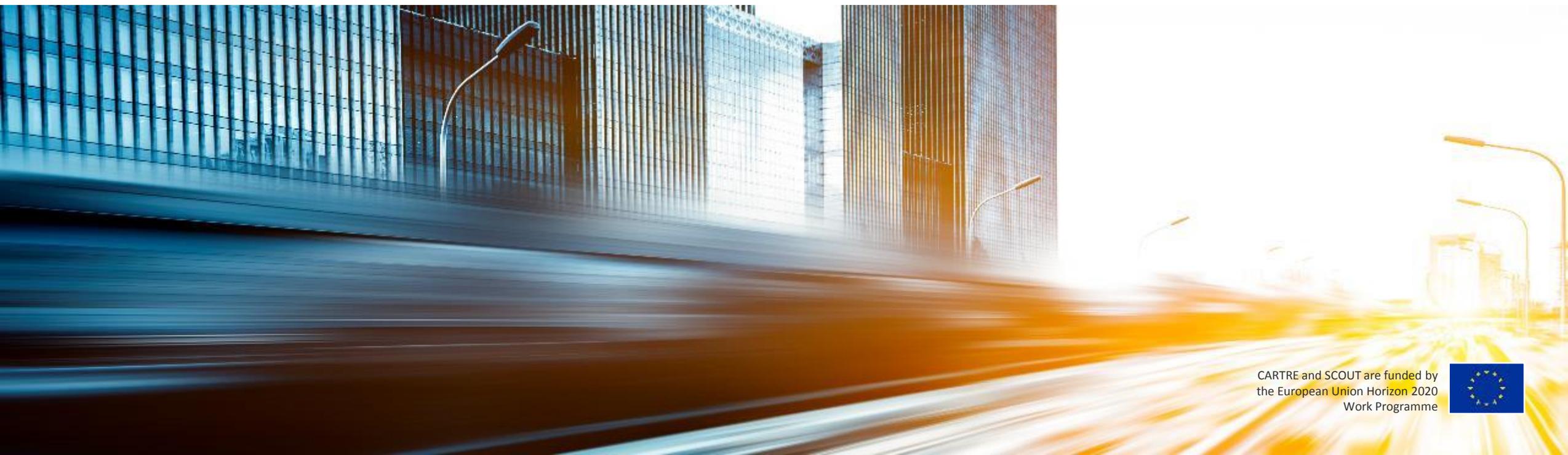




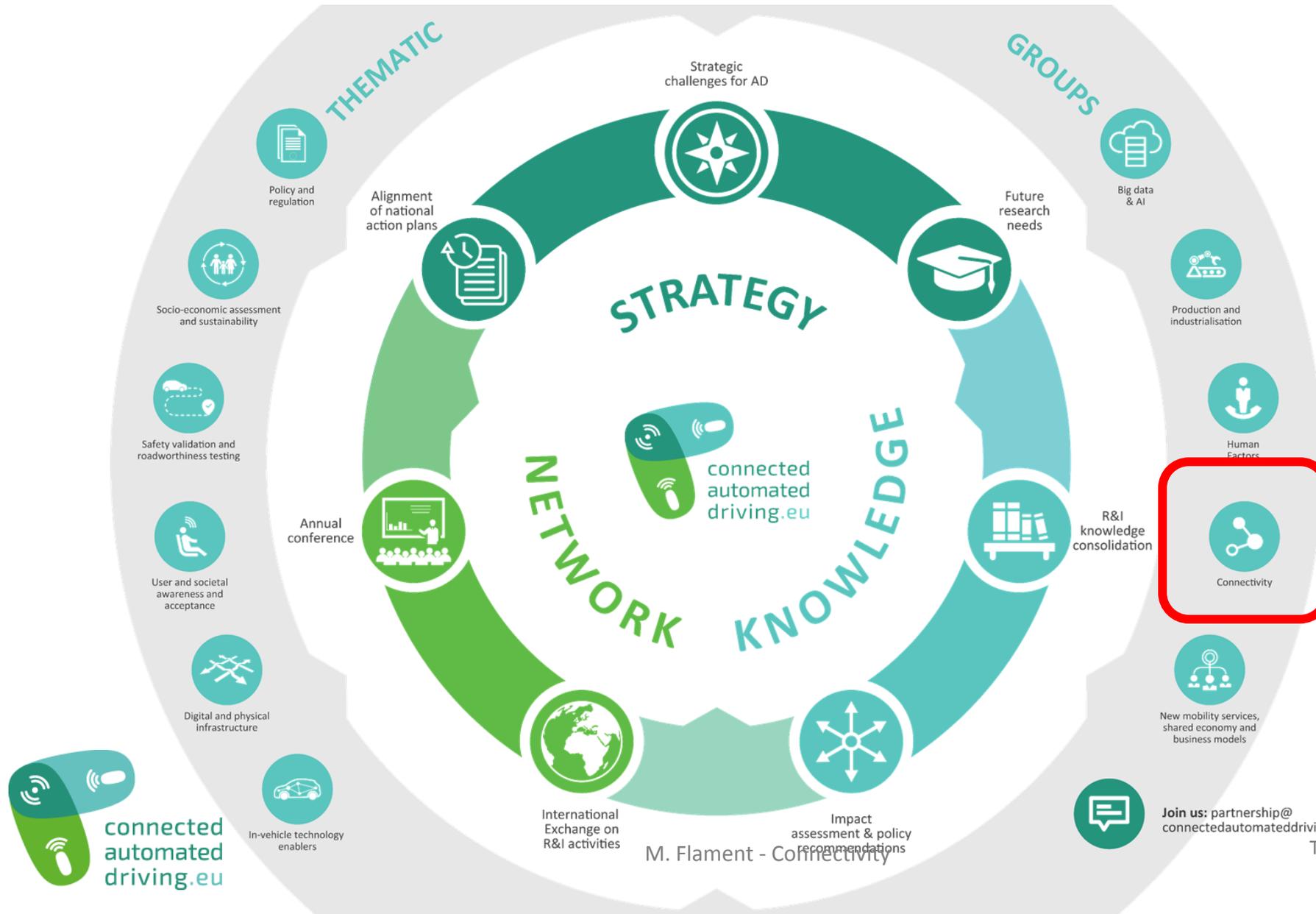
# Connectivity for Automated Driving *Needs and Challenges*

*Maxime Flament, ERTICO – ITS Europe*



# CARTRE: Coordination action for Automated Road Transport For Europe

Objective: Support faster deployment of connected and automated driving across Europe



- October 2016 – September 2018
- Coordination & Support Action
- 2 EU-funded Projects
- CARTRE SCOUT**  
Coordination of Automated Road Transport Deployment for Europe
- 36 consortium partners
- 30+ associated partners

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Cooperative Urban Level1-2 Cellular  
Connected Highway Level4-5  
Low Latency Private Shared Fleet V2I Edge  
Back-office C-V2X 3GPPP V2V V2N  
QoS 802.11p ETSI OEM Cloud  
5G IEEE NB-IoT Traffic Manager  
Service Cloud  
APIs

# Connectivity

For Automated Driving



# CARTRE thematic area Connectivity consolidates many inputs from different European Initiatives

Digital  
Economy

CAD  
RoundTable

GEAR2030

C-ITS  
Platform

5GPPP

5GAA

EATA

AIOTI

ERTICO  
CAD

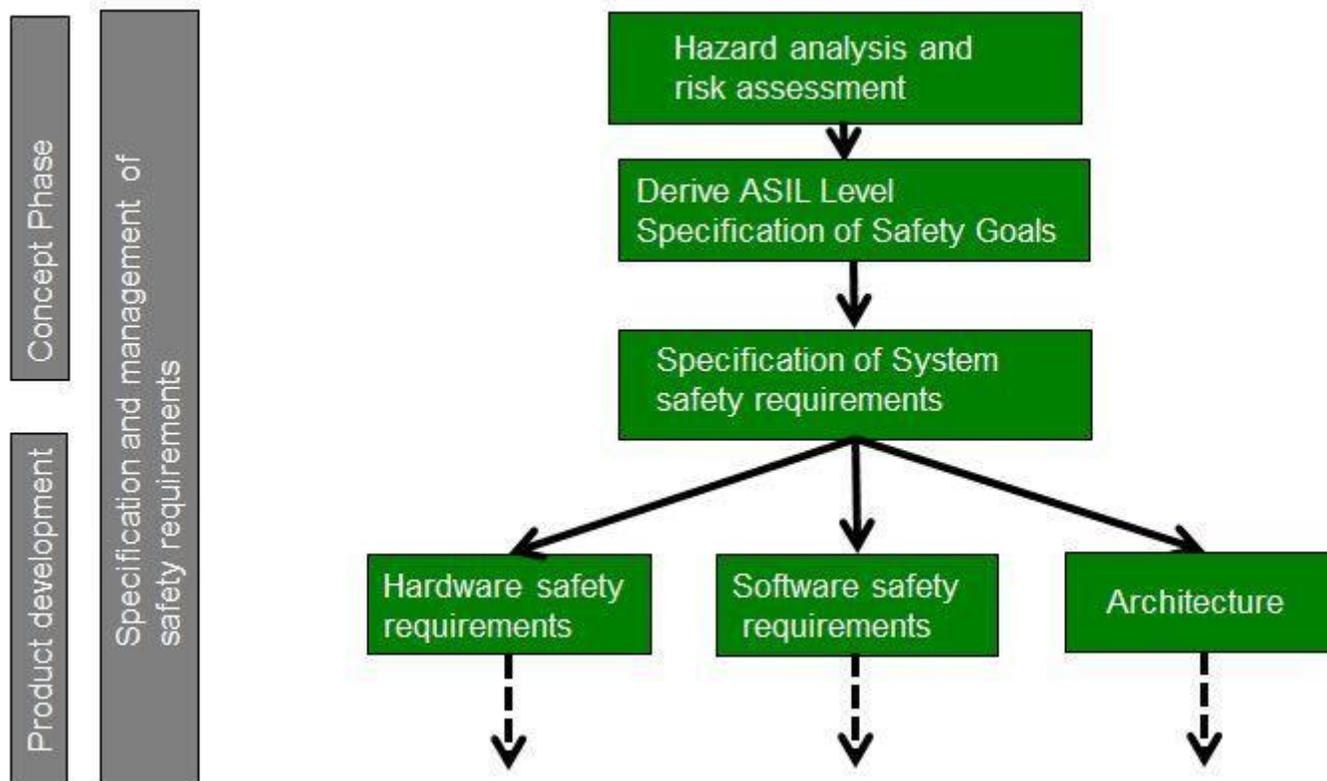
[...]

***“High Level Group GEAR 2030 report on automotive competitiveness and sustainability”***

<https://ec.europa.eu/docsroom/documents/26081>

# Statement 1:

## Current C-ITS standards do not yet answer the needs for automated driving and safety critical applications



### Risk Assessment:

Numerous unknown along data chain:

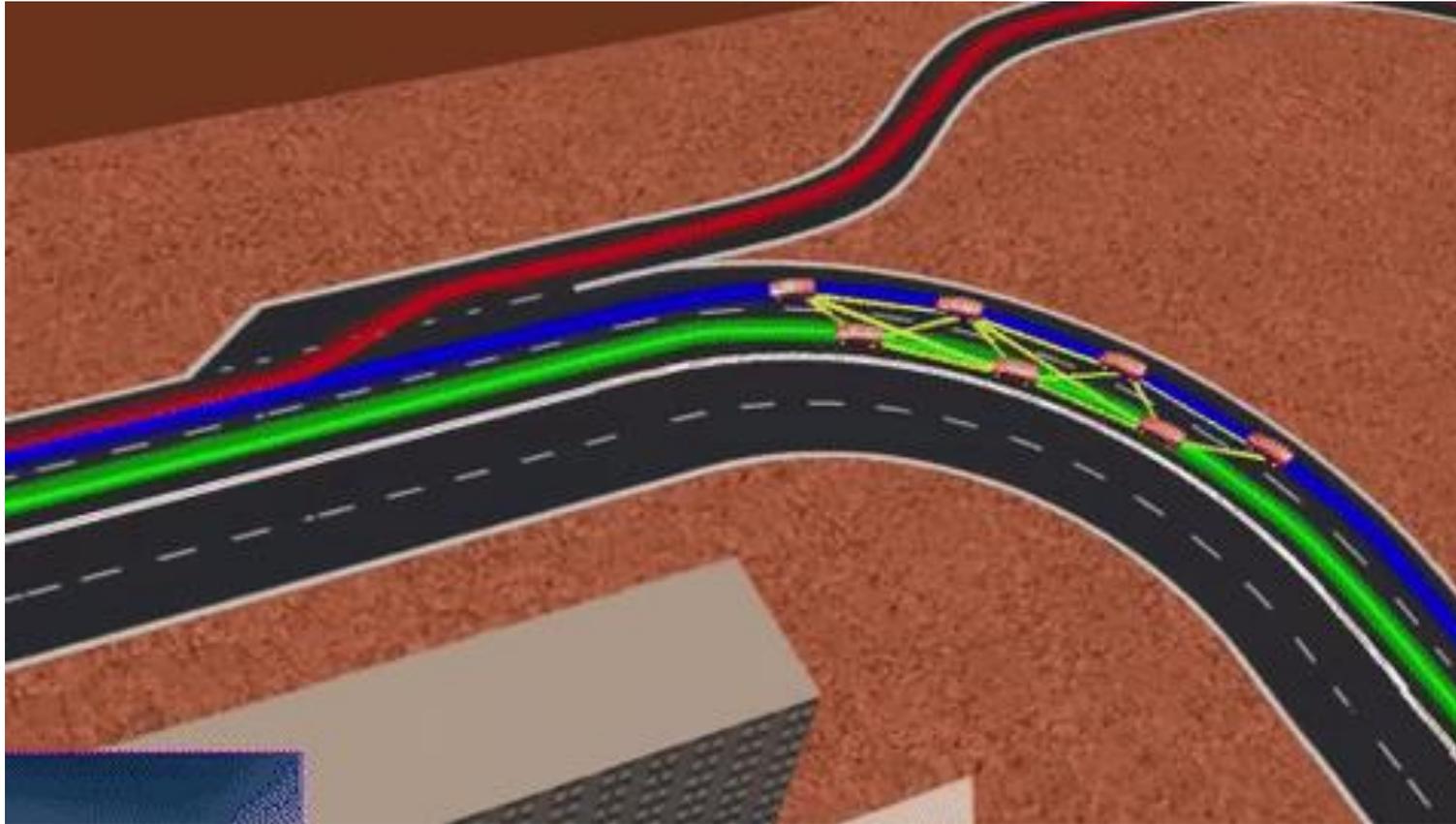
Position and sensing quality,  
Map Matching,  
Vehicle warning triggers ,  
Message error and integrity,

No guaranteed quality

Source: ISO 26262/Functional Safety - embitel

## Statement 2:

# There will be a need for a next generation of V2V-V2I protocols and communication technologies



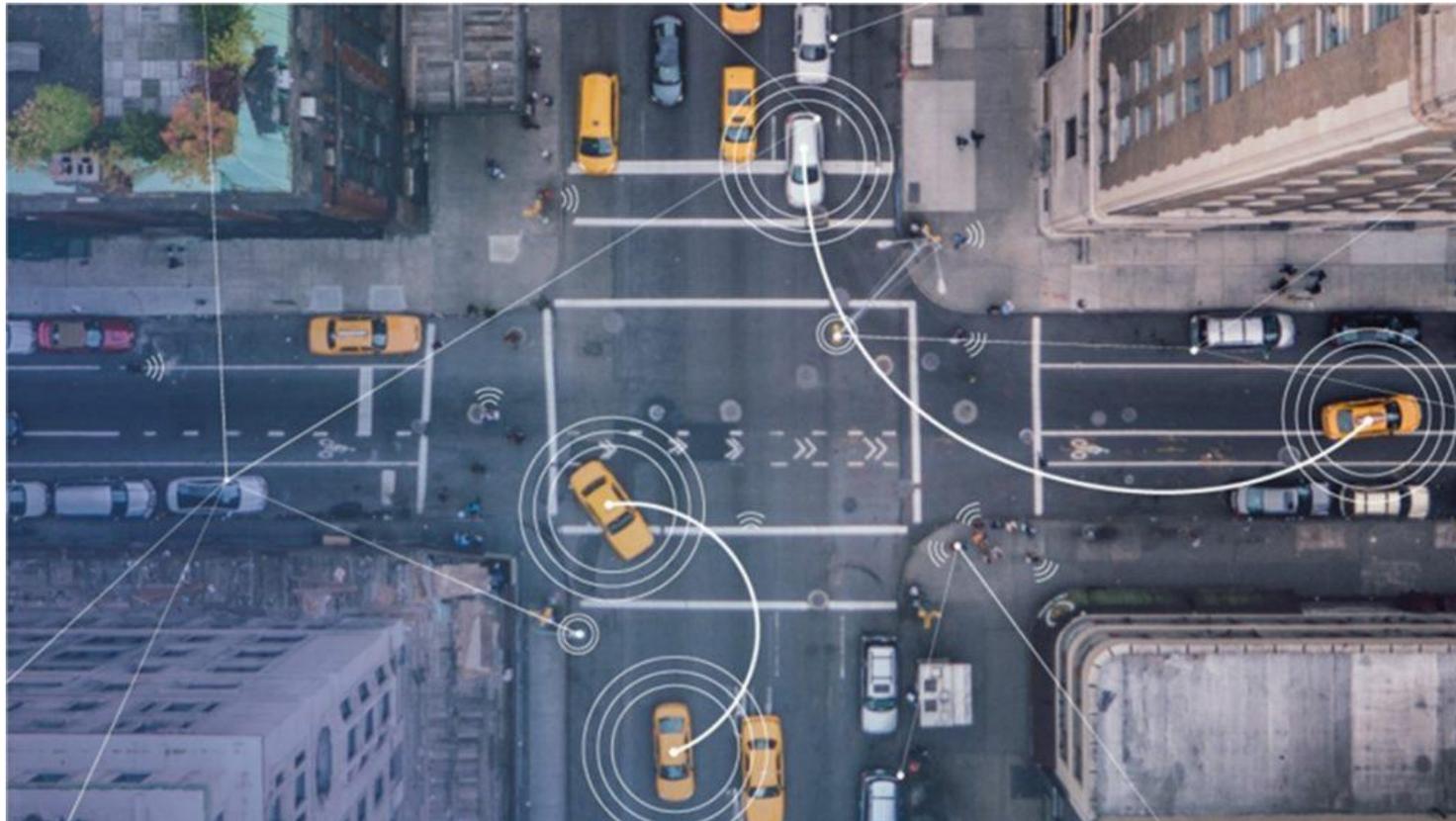
### Next steps:

- Short range secure exchange of sensor and maneuvering data
- high degrees of reliability and quality control.



## Statement 3:

**Lower levels of automation cannot (and will not) wait for wider penetration of the V2V/V2I short range communication.**

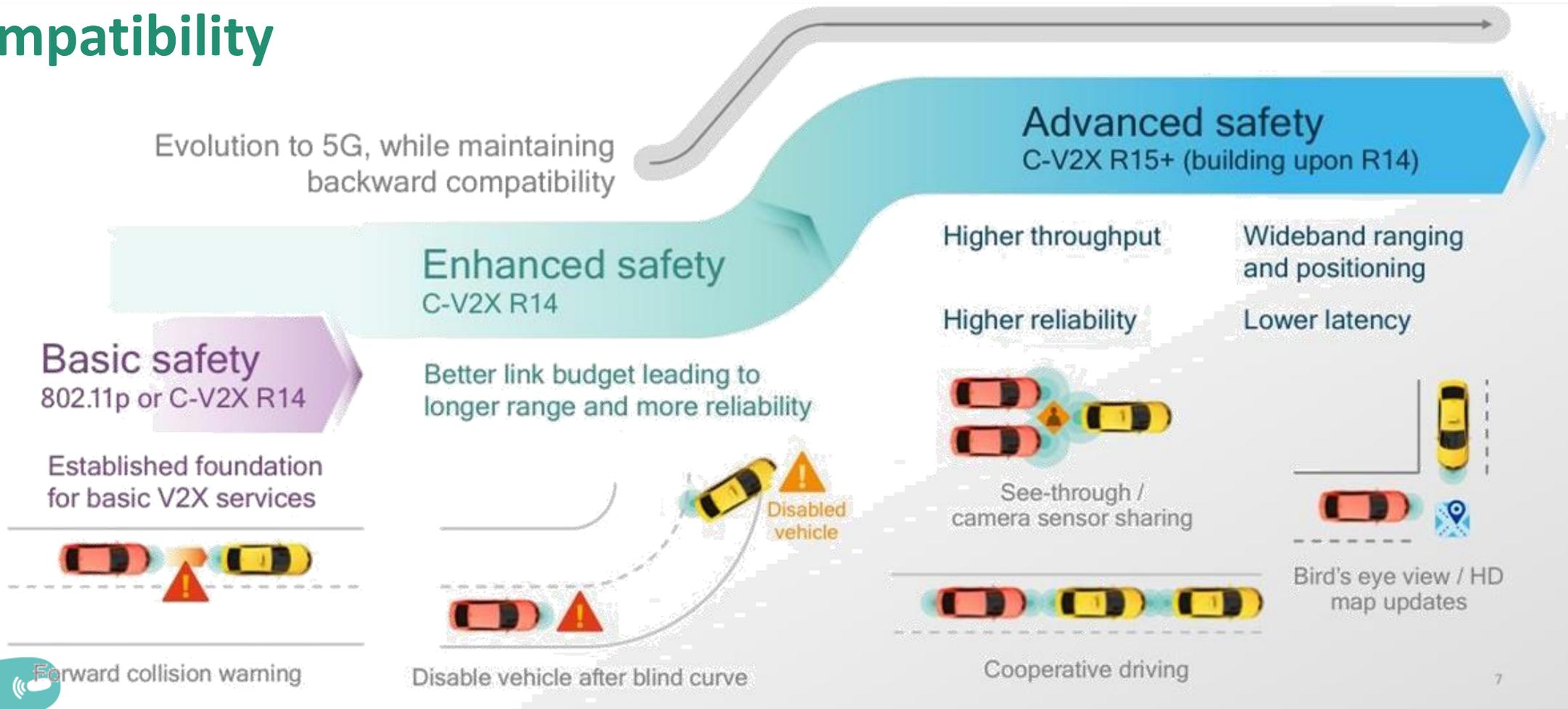


Source: Intel

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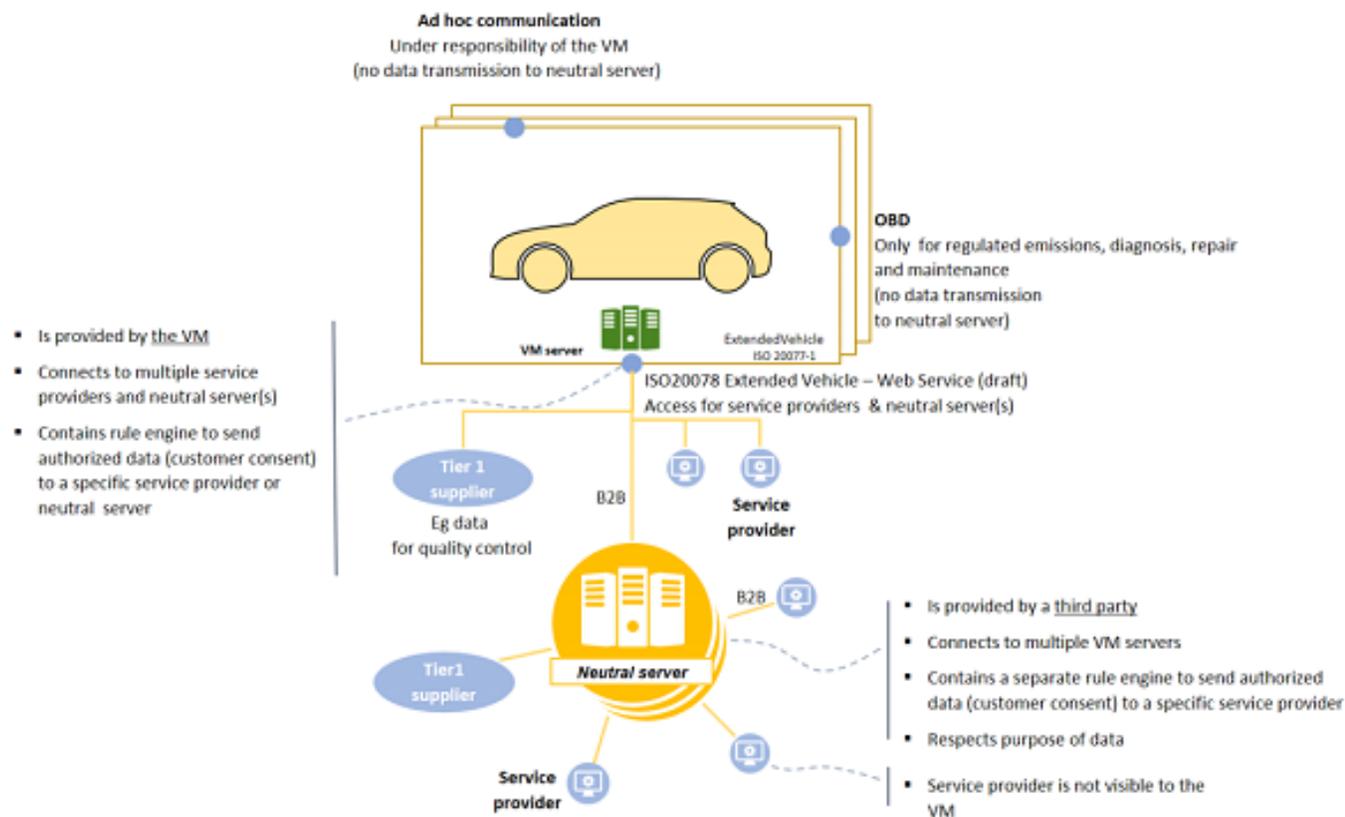
## V2X communication stack needs further independence between its layers in order to guarantee forward compatibility



# Statement 5:

## Vehicle clouds will be needed as an extension of their sensor platform; APIs will open data to other services

### Extended vehicle, service providers and neutral server(s)



Source: CLEPA/ACEA



# Main outcomes of the connectivity discussions (as reflected in “*High Level Group GEAR 2030 report on automotive competitiveness and sustainability*”)

<https://ec.europa.eu/docsroom/documents/26081>

V2X → Enabler for AD

Fast V2X standardisation for AD (3GPP and ETSI)  
→ Convergence towards 5G

Technology neutrality → market driven approach

Flexible regulatory approaches → stay open to innovation

mission-critical need V2X channels with quality control

# Conclusions

- Connectivity for Automated Driving is still at its infancy but will eventually be needed!
  - C-ITS / DSRC standards at 5.9GHz were not designed with automation in mind
  - There is no guarantee of full penetration of V2X on which automated vehicles can rely
  - New standards will be needed taking the requirements of AD into account
  - Integration of V2X data in the functional safety framework will be a next major step
- Concept of Extended Vehicle and neutral server will prove to be a great support for the next CAD deployment steps