



# Low-Speed Automated Shuttles Foundational Research

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# Overview of Low-Speed Automated Shuttle Market

Vehicles, Manufacturers, and Suppliers



# Low-Speed Automated Shuttles: Major Manufacturers

meet **olli**



**SENSITIVE:** My lidar and optical cameras allow me to see in all directions.

**RESPONSIVE:** My self-driving software allows me to make decisions faster than my human friends and keep everyone safe.

**SYMBIOTIC:** My electric drivetrain protects our environment while providing a quiet ride for my passengers.

**STYLISH:** My exterior is customizable, allowing my look to reflect the style of my riders, city or campus.

**SUPERVISED:** My activity and the safety of my riders are monitored by a human at all times.

LM

**Local Motors**  
*Olli*

NAVYA ARMA

How does it work ?



**MAPPING**  
NAVYA engineers visit the site, map out the area and program the circuit.

**AUTOMATIC**  
The NAVYA ARMA shuttles practice on the programmed circuit. Accurate to within 2cm they detect any changes to the surroundings (obstacles, pedestrians etc.) thanks to multiple technologies.

**GNSS Antenna**

**LIDAR Sensors**

**Stereovision Cameras**

**Odometry**

ID. IL.

**Navya**  
*Arma*

Localization technologies

Safety features



**LOCALIZATION USING DATA FUSION**

- 1) LASERS
- 2) CAMERAS
- 3) GPS
- 4) ODOMETRY
- 5) IMU

**DECISION-MAKING SAFETY CHAIN**

- 1) EMERGENCY STOP BUTTONS X3
- 2) CERTIFIED INDUSTRIAL GRADE SAFETY CONTROL UNITS
- 3) OBSTACLE DETECTION LASERS
- 4) BRAKING SYSTEMS & FAIL-SAFE PARKING BRAKE

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**EasyMile**  
*EZ10*

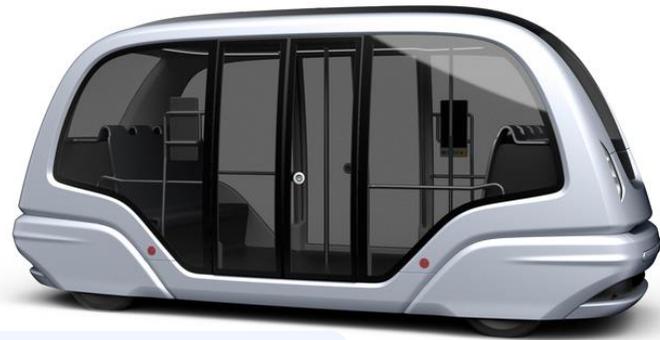
# Comparison of Major Manufacturers



Specification	Local Motors Olli	Navya Arma	EasyMile EZ10
<b>Capacity</b>	12	15	12
<b>Cruising Speed</b>	12 mph	15.5 mph	12 mph
<b>Maximum Speed</b>	30 mph	28 mph	25 mph
<b>Battery</b>	Lithium (unspecified)	LiFeP04	LiFeP04
<b>Battery Capacity</b>	18.5 kWh	33 kWh	20 kWh
<b>Battery Life</b>	Up to 5 hours	Up to 12 hours	Up to 14 hours
<b>Vehicle Weight</b>	4,057 lbs.	5,291 lbs.	3,900 lbs.
<b>Fully Loaded Weight</b>	6,261 lbs.	7,606 lbs.	6,000 lbs.
<b>Sensors</b>	GPS, radar, lidar, camera, ultrasonic	GPS, lidar, camera	GPS, radar, lidar, camera
<b>Communications</b>	DSRC (optional)	DSRC (optional)	

Note. Information in this table comes from multiple specification sheets provided by Local Motors, Navya, and EasyMile; specifications may differ slightly vehicle to vehicle.

# Low-Speed Automated Shuttles: Other Manufacturers



**2getthere**



**Westfield Sportscars/  
ULtra Global PRT**



**2getthere**



**RDM Group**

# Low-Speed Automated Shuttles: Retrofit Vehicles



**Auro Robotics**



**Varden Labs Alvin**



**TARDEC (ARIBO)**

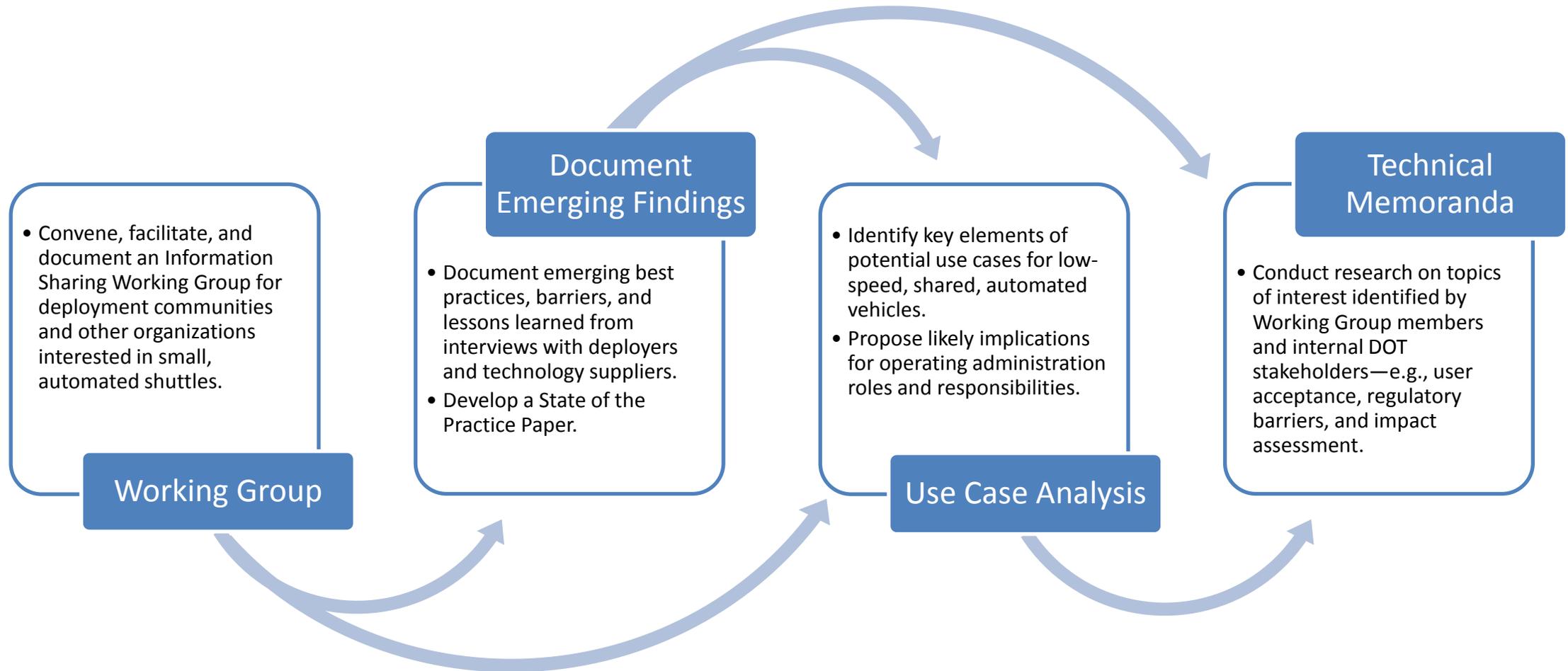


**Waymo Minivan**

# Project Overview

Tasks and Approach

# ITS JPO/ Volpe Project Overview



# Low-speed Automated Shuttle Information-sharing Working Group



# Treasure Island Shuttle



## Organizations

- San Francisco County Transportation Authority (SFCTA)
- San Francisco Municipal Transportation Agency (SFMTA)

## ATCMTD Grant

- \$10.9 million award from the Advanced Transportation and Congestion Management Technologies Deployment (ATCMTD) grant program
- Funds will be used to creating dynamic pickup curbs for ridesharing and carpooling, set up regional carpool lanes, install smart connected traffic signals, deploy a connected tolling system and create an automated shuttle service.



Source: SFCTA

## Treasure Island Shuttle

- In addition to SFCTA and SFMTA, partners include Treasure Island Development Authority and UC Berkeley
- Automated shuttle service to carry passengers around Treasure Island and Yerba Buena Island
- Planning work has suggested a system with three 12-pax shuttles, though the number of shuttles and their specifications have not been set

# ARIBO Shuttle



## Organizations

- U.S. Army Tank Automotive Research Development and Engineering Center (TARDEC)
- Robotic Research, LLC



## Applied Robotics for Installations and Base Operations (ARIBO)

- Three different locations: Fort Bragg (NC), Fort Leonard Wood (MO), and West Point (NY)
- Multi-phase approach: Phase 0 (development), Phase 1 (human operation), Phase 2 (human supervision), Phase 3 (unmanned operation)

## Fort Bragg Project

- Began in 2014 and transitioned to Greenville, NC in August 2017
- On-demand transport for soldiers and staff around the WTB barracks and Womack Medical Center
- Five pickup/drop-off locations on a route that includes a four-lane divided road, intersections, parking lots, patient drop-off locations, and walkways
- The base platform is a Cushman Shuttle 6 electric vehicle



Source: FHWA Public Roads 80(2)

## Interface & Monitoring

- Scheduling System with kiosks and smartphone application
- Text-based reminder system
- Remote monitoring (cameras inside and outside of the vehicle)
- On-board black-box data recorder

# University of Michigan Shuttle



## Organization

- Mobility Transformation Center, University of Michigan

## Mcity Testing

- In December 2016, Mcity began working with a Naveya Arma shuttle.
- The shuttle has been used to conduct research and provide tours.

## North Campus Pilot

- Beginning in fall 2017, the shuttles will be used in a new campus mobility service for students, faculty, and staff.
- The shuttles will drive along a two-mile route between the Lurie Engineering Center and the North Campus Research Complex (NCRC), picking up passengers every 10 minutes.
- The study will examine passenger reactions and user acceptance of the technology.



Source: University of Michigan

# Minnesota Automated Bus



## Organization

- Minnesota Department of Transportation (MnDOT)

## Automated Bus RFP

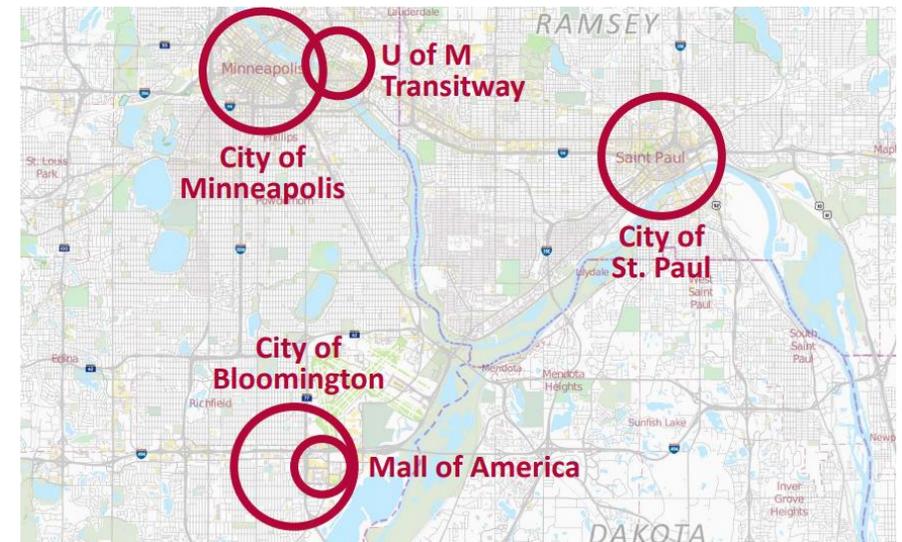
- MnDOT issued an RFP for an automated bus demonstration, but it did not receive proposals for automating a full-size bus that met its goals, so it is focusing on low-speed automated shuttles.

## Testing and Demonstration

- MnDOT is leasing a shuttle for the testing and demonstration.
- Initial testing at MnROAD will include cold-weather testing with ice, snow, and wind.
- The project will culminate with a five-day demonstration in early February during the Super Bowl (demonstration site TBD).



Source: EasyMile



Source: MnDOT

# City of Arlington, Texas



## Organization

- City of Arlington

## Demonstration

- The Arlington Convention Center was the third stop of the “2017 Autonomous Vehicle Road Trip” event in February 2017.
- Community and media were invited to attend, and Arlington City Council members were among some of the first riders.

## Milo Pilot Project

- In March 2017, the Arlington City Council approved a one-year lease agreement for Two EasyMile EZ10 shuttles.
- In August 2017, shuttles began providing rides to the general public along select off-street trails in the Arlington Entertainment District.



Source: City of Arlington, TX



Source: City of Arlington, TX

# Site Visits and Interviews



## Site Visits

- ARIBO shuttle at Fort Bragg, NC
- GATEway pods in Greenwich, UK
- Michi-no-eki in Japan
- Navya shuttle at Mcity, MI
- Valley Metro, AZ

## Industry Interviews

- 2getthere
- BestMile
- Coast Autonomous
- *Delphi - Upcoming*
- EasyMile
- Local Motors
- May Mobility
- Navya
- Panasonic
- *Optimus Ride - Upcoming*

## Deployer Interviews

- Arlington, TX
- Atlanta, GA
- Boston, MA
- Contra Costa, CA (GoMentum Station)
- Denver, CO
- Fort Bragg, NC (TARDEC)
- Greenville, SC
- Jacksonville, FL
- Kansas City (KCATA)
- Los Angeles (Access Services)
- Mcity, MI
- Middletown, PA (PennDOT)
- Phoenix Metro (Valley Metro)
- Pinellas County (PSTA)
- Twin Cities, MN (MnDOT)
- Santa Clara, CA (University and VTA)
- United States Marine Corps

# Tracking the Deployment Landscape

## 25+ Demonstrations and Pilots in Asia

- Auto Riders (EasyMile EZ10) @ Gardens by the Bay – Singapore
- MOLIT-Hyundai Shuttles for 2018 Winter Olympics – South Korea

## 60+ Demonstrations and Pilots in Europe

- CityMobil2 (EasyMile EZ10) – Multicity
- SOHJOA (EasyMile EZ10) – Finland
- Deutsche Bahn Pilot (Local Motors Olli) – Germany

## 50+ Demonstrations and Pilots in North America

- Mcity tours and testing (Navya Arma) – Ann Arbor, MI
- Transdev/ EasyMile nationwide demo tour – Multicity

## 5+ Demonstrations and Pilots in Oceania

- Waterfront circulator (EasyMile EZ10) – Australia
- Airport pilot (Navya Arma) – New Zealand



Image Sources:  
EasyMile, Navya Tech &  
Deutsche Bahn AG

# Use Cases

## **Use Case Analysis (*currently in progress*):**

Identifying potential points of interest and/or relevance for U.S. DOT modes in plausible automated community shuttle use cases.

<b>Agency Responsibilities</b>	<b>Service Characteristics</b>	<b>Vehicle Characteristics</b>
<ul style="list-style-type: none"><li>• Civil Rights</li><li>• Data</li><li>• Freight</li><li>• Fuel Economy</li><li>• Grants Administration</li><li>• Infrastructure</li><li>• Planning</li><li>• Safety</li><li>• Management &amp; Operations</li></ul>	<ul style="list-style-type: none"><li>• Operating Environment</li><li>• Path/Route</li><li>• Waypoint</li><li>• Schedule</li><li>• Cargo Type</li><li>• Revenue Service</li><li>• Interstate Commerce</li><li>• Specialized Infrastructure</li><li>• Federal Funding</li><li>• Human Operator</li></ul>	<ul style="list-style-type: none"><li>• Remote Intervention</li><li>• Weight</li><li>• Maximum Speed</li><li>• Maximum Capacity</li><li>• Powertrain Type</li></ul>

# Preliminary Findings

*Based on Working Group meetings, stakeholder interviews, site visits, ongoing use case analysis, and literature review*

# Key Findings

- **Market overview**

- The marketplace is rapidly evolving, with many new companies.
- Partnerships and roles are constantly changing.

- **Activity overview**

- There are dozens of pilots and demonstrations worldwide.
- Most projects are testing technology feasibility and basic user acceptance.
- Deployments are largely passenger-oriented, but some are interested in freight use cases.
- Additional attention is needed on accessibility and universal design.
- Most deployments have used onboard operators.
- Deployers are generally proceeding with caution.

- **Known challenges**

- Both technical and policy/institutional challenges remain.
- Further piloting will be required to understand use cases, costs, benefits, and demand.

# Known Challenges

- **Technical**

- Constrained to low speeds and highly controlled environments
- Need for operator interventions and stops
- Limited accessibility for travelers with disabilities
- Tradeoffs in service type
- Interactions with other road users and animals
- Operation in inclement weather and extreme conditions
- Perception of signs and traffic lights

- **Policy/Institutional**

- Safety validation and certification
- Vehicle accessibility requirements
- Requirements related to federal funding
- Regulations regarding remote intervention
- Uncertain passenger demand

# For More Information

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