

SIP-adus Workshop 2020 Workshop on Regional Activities

# **Automated Driving in Germany**

German Test Beds and UNICARagil as a Flagship Project

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### **Overview on German Activities** Pilot Tests with automated Shuttle Vehicles

- Many pilot tests on automated shuttles are running or planned
  - Private property and public road
  - Mainly low speed operation up to 15 kph
  - Very "easy" and controllable routes
  - Safety guard or driver on board
- Special permissions needed and are in responsibility of local authorities
  - Government is working on legislation for automated driving with level 4 and 5

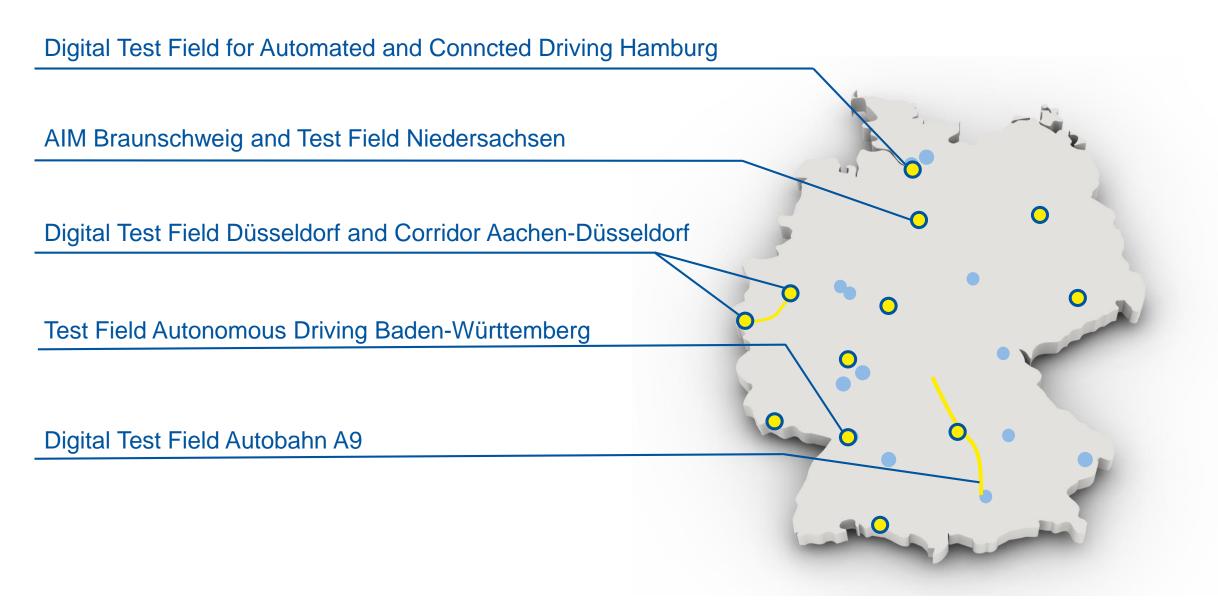




## **Overview on German Activities**

Digital test beds for connected and automated driving in real Traffic





# **Overview on German Activities**

Digital test beds for connected and automated driving in real Traffic



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## Digital Test Field for Automated and Conncted Driving Hamburg

AIM Braunschweig and Test Field Niedersachsen

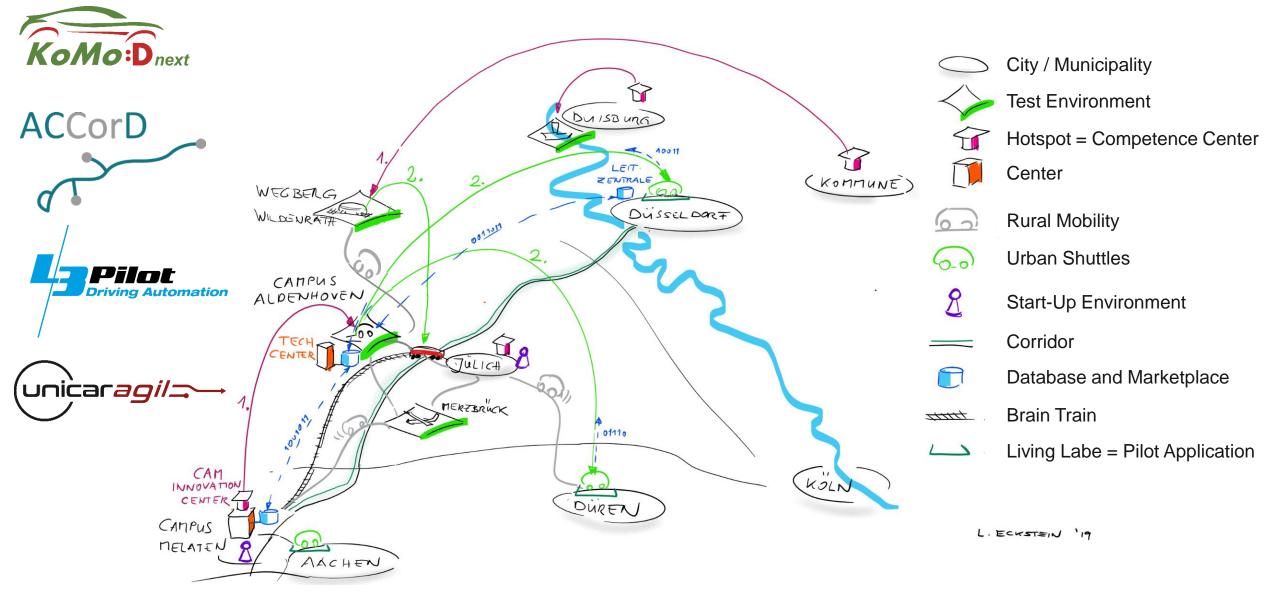
Digital Test Field Düsseldorf and Corridor Aachen-Düsseldorf

- KoMoD and KoMoDnext projects:
  - Testing of automated and connected functions on motorways and in urban areas
  - Connection of infrastructure and traffic management systems
  - Level 4 valet parking
- ACCorD project
  - Connecting the research campus Aachen to the Test Field Düsseldorf
  - Generation of reference data for function development and safety assurance

# Test Field Autonomous Driving Baden-Württemberg

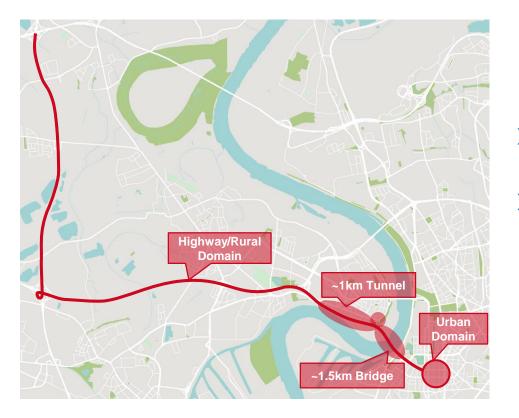
# Digital Test Field Autobahn A9





# ika @ KoMo:Dnext

Automated Driving in the Digital Test Field Düsseldorf



- ODD-Support Information for a-priori takeover-request or replanning of route
- Communication via ITS-G5 (802.11p) and Cellular Communication



aufgrund eines Beschlusses des Deutschen Bundestages

- Development of a cross-domain driving function for lateral and longitudinal vehicle guidance
- Implementation of V2I Interfaces and usage in driving function



# ACCorD **Corridor for New Mobility Aachen – Düsseldorf**



### **Project goals:**

- Establishment of reference sensor technology
- Acquisition of traffic data, trajectories and scenarios
- Investigation of new driving functions and infrastructure measures in the simulation
- Replication and testing of selected scenarios on the test track
- Roll out the functions and actions into the field
- Linking existing test fields

### Track sections with infrastructure sensors:



Urban Campus Melaten, Aachen 2.4 km, 46 measuring stations

Aldenhoven

Test field

Campus Melaten, Aachen

Aachen

NTH/

Test field

A 44

Aachen

Rural B 56. Aldenhoven 1 km, 11 measuring stations

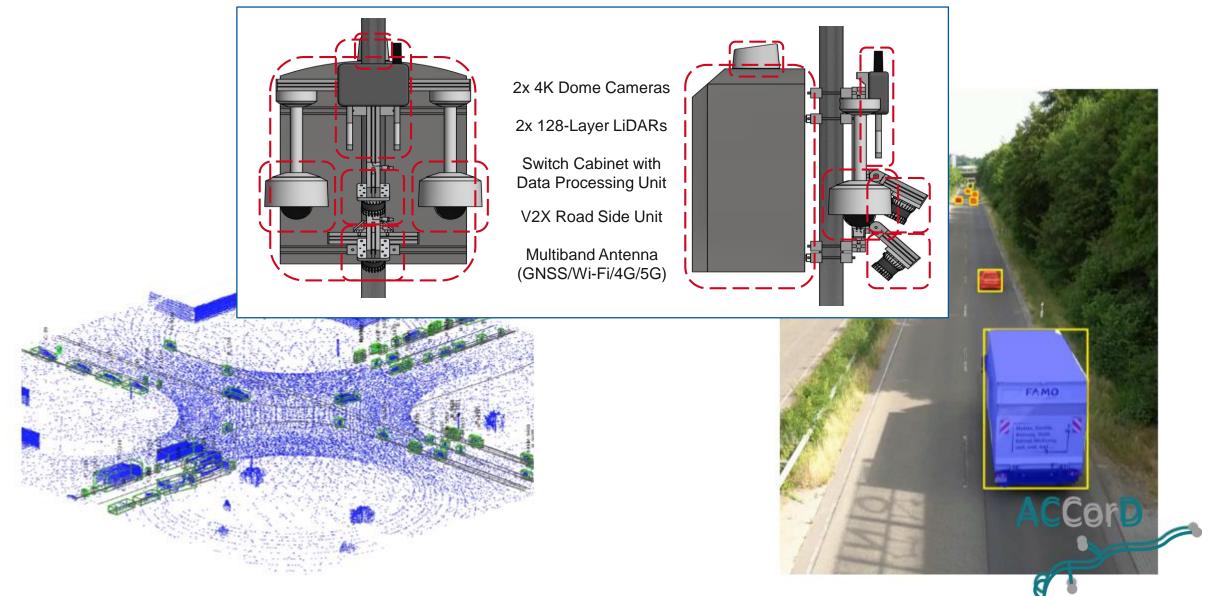


Highway A 44, highway junction, Jackerath 1 km, 11 measuring stations



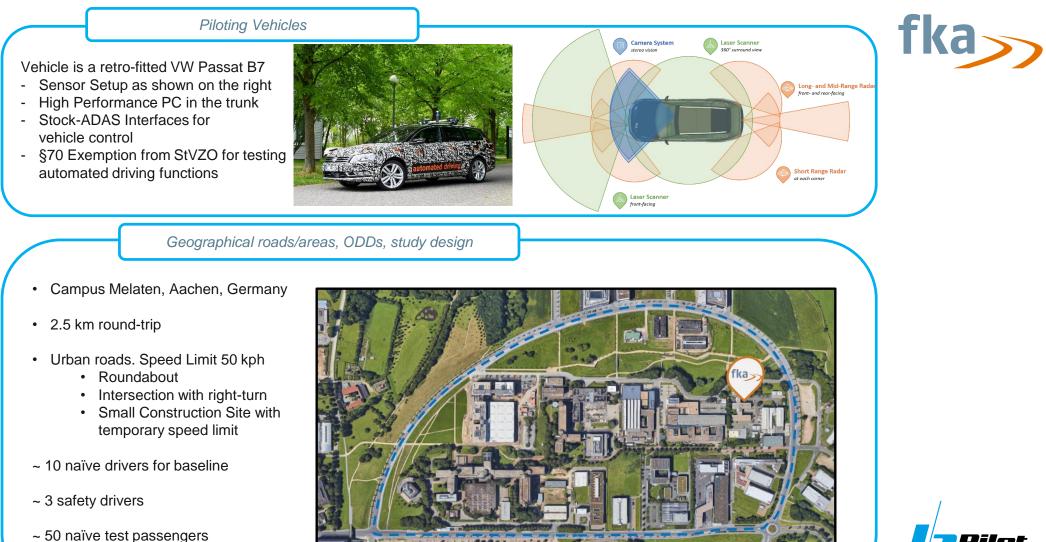
# ACCorD Hardware Concept





# Field operational tests on higher level of automation EU Project L3Pilot – Pilot tests in Aachen





~ 500 km planned



# Field operational tests on higher level of automation EU Project L3Pilot – Outlook to Hamburg 2021







- L3Pilot is testing Automated Driving in Hamburg
  - More than 120 test persons drove through the center of Hamburg, Germany, in fully equipped research vehicles of Volkswagen AG
  - fka GmbH from Aachen is planning to drive in Hamburg 2021
- Laying the foundation for level 4 field tests in follow up activities

**Pilot** Driving Automation

#### Sources:

- Volkswagen AG (https://www.volkswagen-newsroom.com/)
- L3Pilot Website (https://l3pilot.eu)
- fka GmbH
- TAVF HH

# Example Project of Level4+ Automation UNICARagil



# KEYFACTS



ca. 26 Mio. € BMBF funding

01.02.2018 - 31.01.2022 (48 months)

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15 university chairs / institutes 8 industrial partners

# OBJECTIVE

- . Modular structures for agile, automated vehicle concepts
- 2. Disruptive concepts in hardware and software architecture
- 3. Modular platform with dynamic modules
- 4. Fully automated and driverless vehicles
- 5. Four prototypes of different characteristics

SPDNSORED BY THE



# Example Project of Level4+ Automation UNICARagil – Core Innovations



Our user-centered design approach focusses on the human being as the center for future mobility system development.

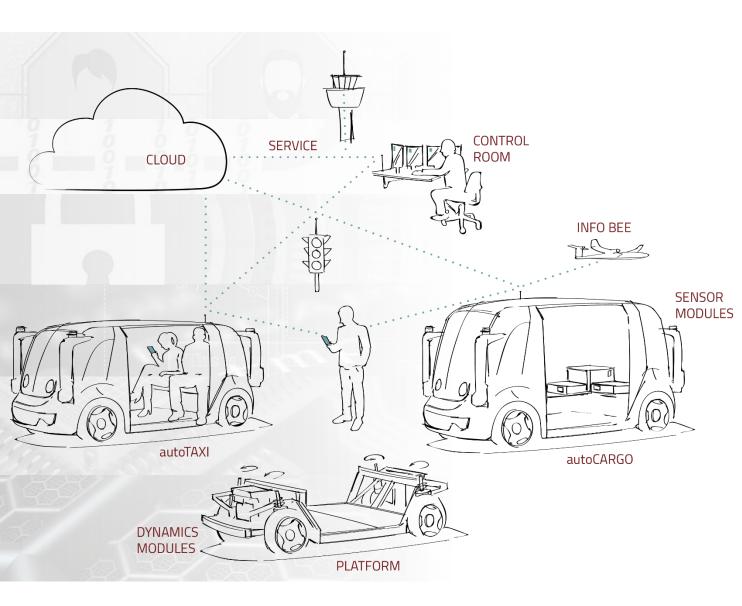
Cooperative and collective cloud functions and an accompanying control room assure the availability of the vehicle automation.

Safety by Design: Consistent safety orientation enables the development of safe autonomous vehicles from idea to approval.

The automotive service-oriented software architecture (ASOA) is the basis for upgradeable and updatable software for automated mobility.

Our innovative electronics system hardware architecture enables the implementation of efficient and safe ECUs.

**Consequent modularization** creates flexibility in the usage of automated vehicles.





Supplementing the public transport system
6 - 8 persons

 Order, open, interact with CE device

• Cooperative and agile

Private "Butler / Nanny"
Private, individual, accessible & trustworthy

Pick up and delivery service
Automated handover









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