

Towards Homologation of Sensors, Sensor Fusion and Automated Driving Function: the Role of high fidelity Environment Modeling

SIP-adus Workshop 2020

Prof. Dr. Stefan SchneiderAdvanced Driver Assistent SystemsUniversity of Applied Sciences in Kempten, Bavaria, Germany



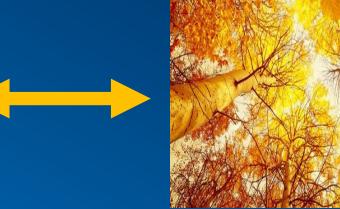




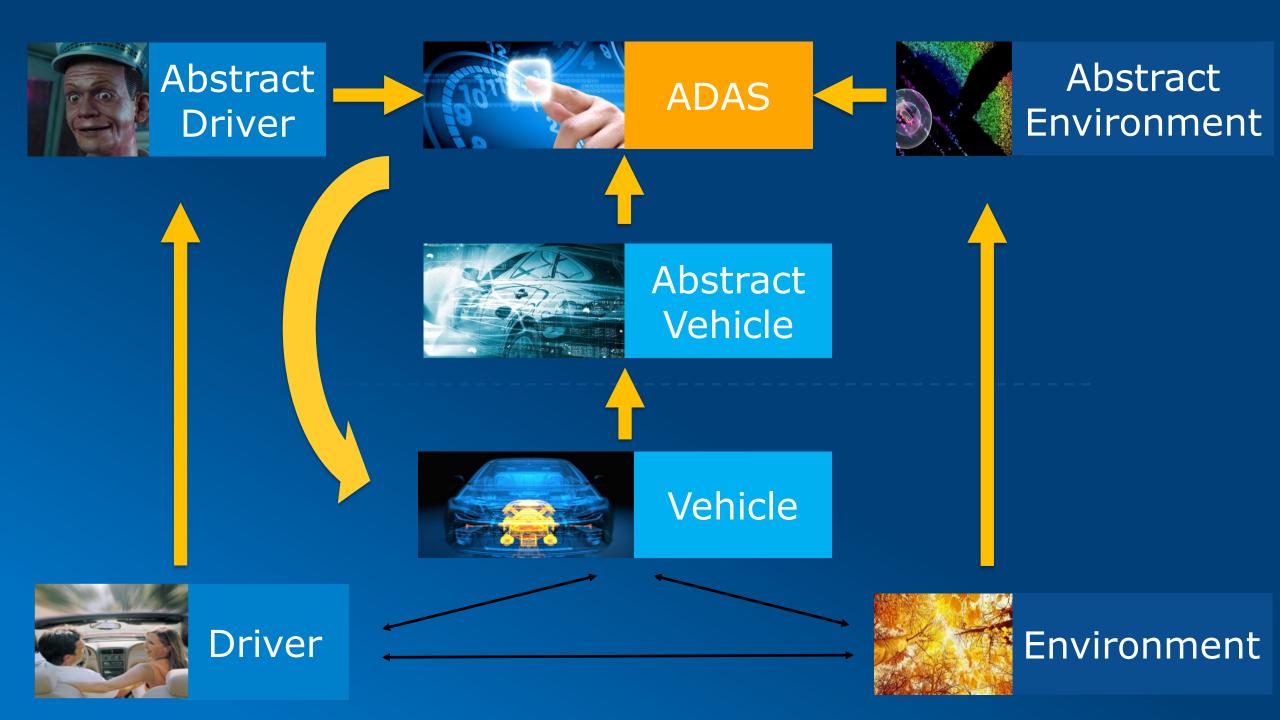
Vehicle

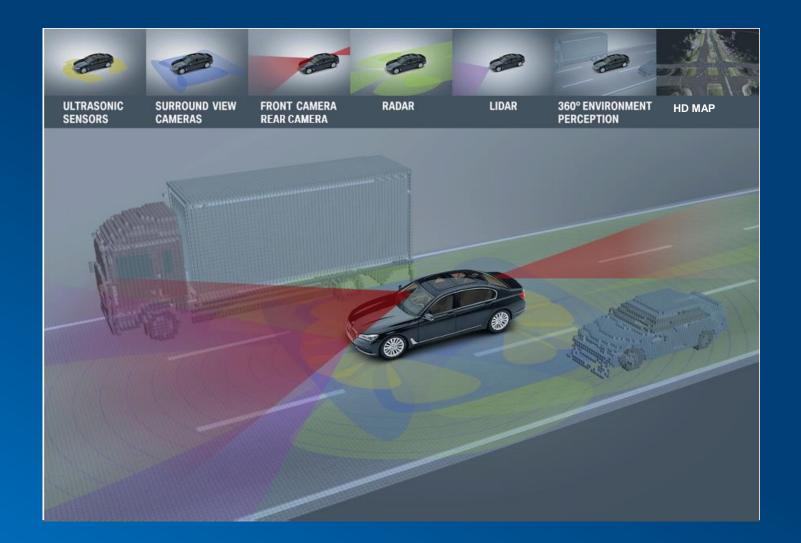




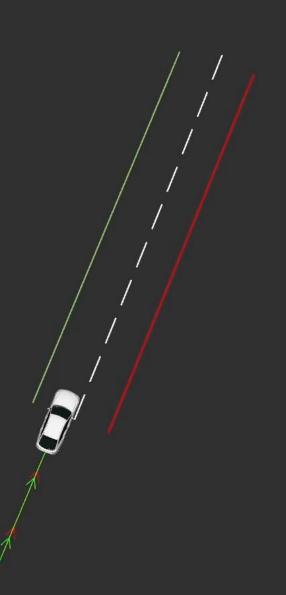


Environment









Validation	Accidents Involving Personal Injury	Driving Performance	Distance Between Two Injury Accidents
Germany all road vehicles	300.000	7,1·10 ¹¹ km	2,0 Mio. km
Germany cars	180.000	6,0·10 ¹¹ km	3,3 Mio. km
Motorways all road vehicles	≈18.000	2,2·10 ¹¹ km	12,0 Mio. km

Driven Miles

Billions of miles of road test will be needed to validate the safety of an autonomous vehicle . . .



Driving to Safety How Many Miles of Driving Would It Take to Demonstrate Autonomous Vehicle Reliability?

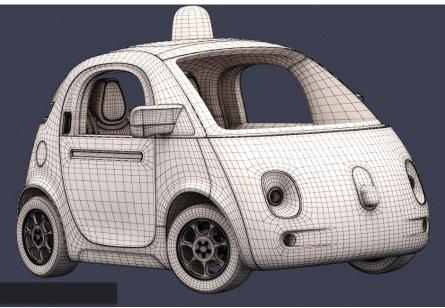
≈ 250 round trips to the moon

Validation

Simulation is the only practical way to validate autonomous vehicles over millions of driving scenarios

Case Study: Waymo





4 Million Road Miles

Driven in NINE Years

0.0.0.0.0.0.0.0.0.0.0.0

A REAL PROPERTY OF THE PARTY OF

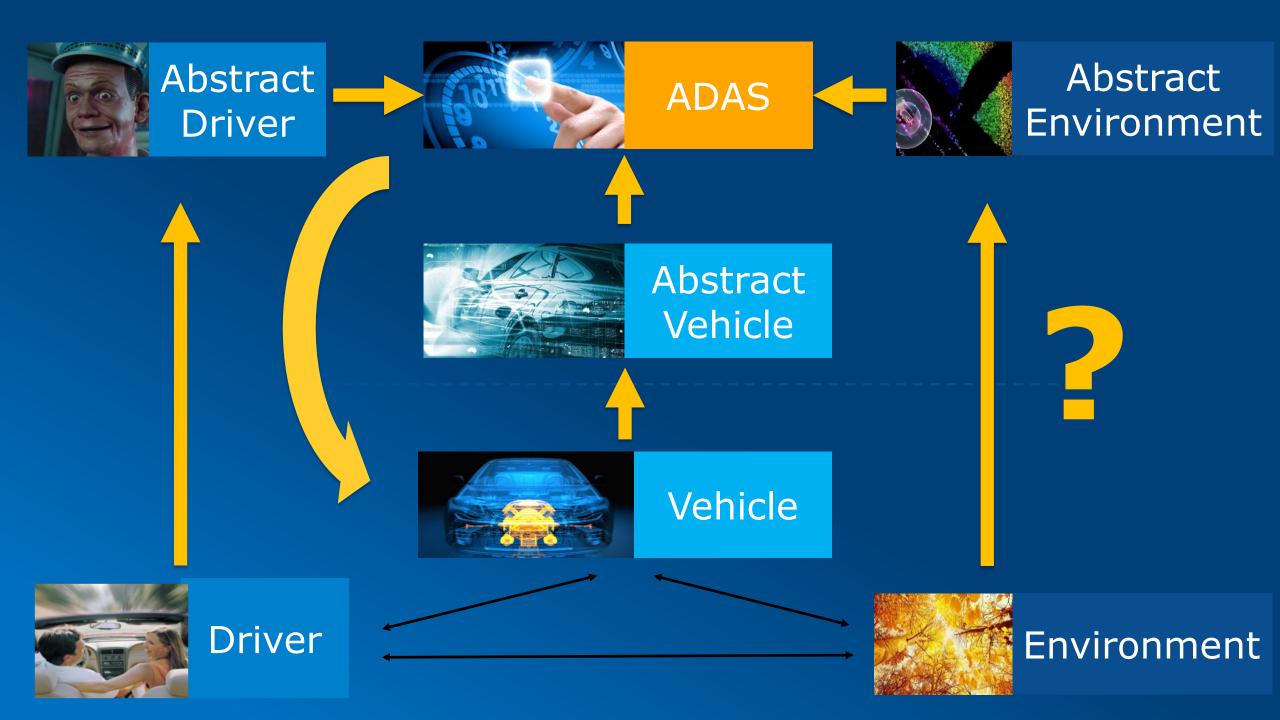
2.5 Billion Simulated Miles

Driven in ONE Year

0.0

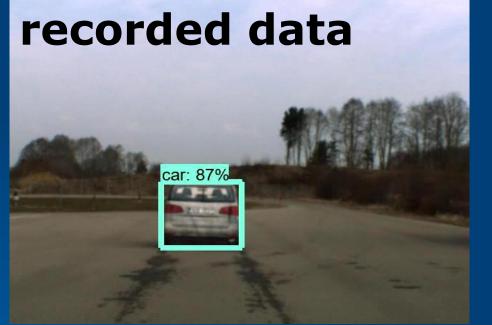
Reference: Waymo Safety Report





















Moving Objects in Sensor Output: 0 Moving Objects in Ground Truth: 1

-

Press H for Help

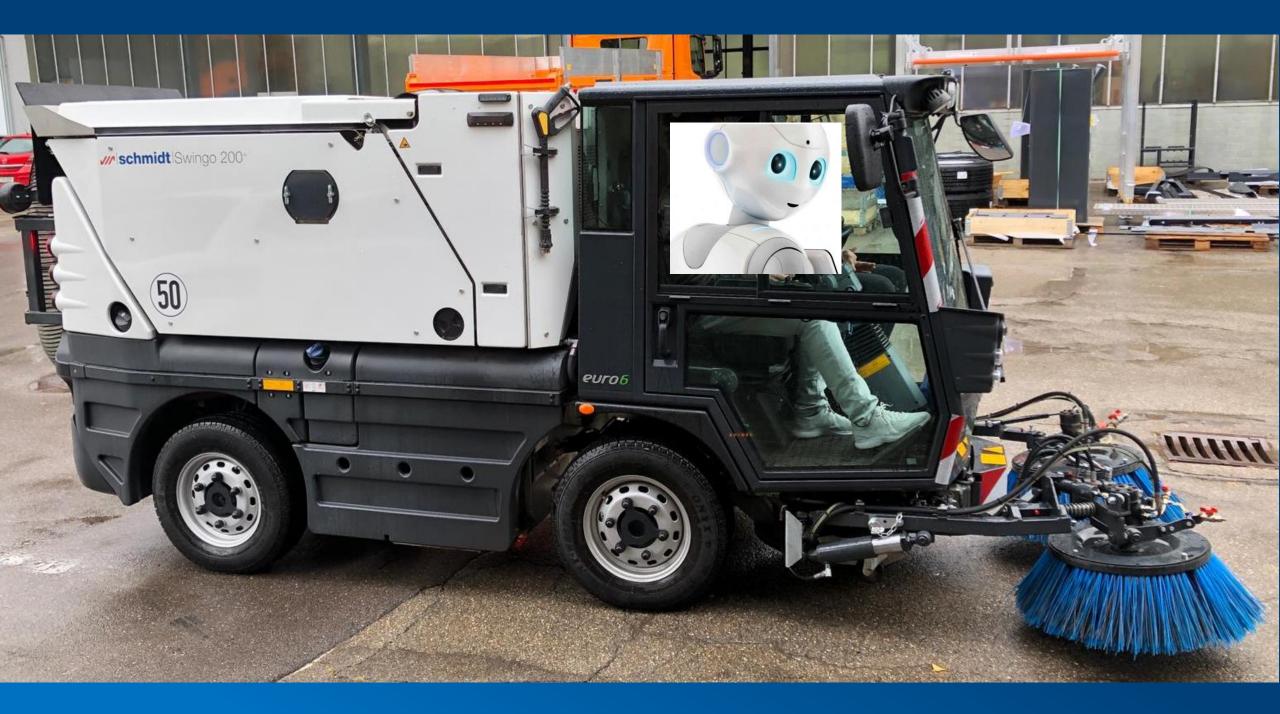
BUUBBUU

Simulation Timestamp: 5 Callouts (Toggle C):

5.900 Off

PMSF

IT Consulting





Hochschule Kempten University of Applied Sciences

ありがとうございました

SIP-adus Workshop 2020

Prof. Dr. Stefan Schneider

Advanced Driver Assistent Systems

University of Applied Sciences in Kempten, Bavaria, Germany