

Next-Generation Intelligent Transport Systems (ITS) utilizing ICT

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- 1. MIC* Research Activities for Next-Generation ITS**
- 2. Development of V2V and V2I Communication Technology for Automated-Driving Systems (Theme 1)**
- 3. ITS-Connect Promotion Consortium in Japan**

***MIC: Ministry of Internal Affairs and Communications in Japan**

Next-Generation ITS utilizing ICT

- MIC plans to realize an advanced Safety Driving Support system.
- The system can prevent traffic accidents on the basis of information transmitted by V2X (V2V, V2I, and V2P) communications, as well as information collected by Infrastructure Radars.
- The feasibility of systems are going to be demonstrated on public roads.

Theme 1

■ Vehicle-to-Infrastructure (V2I) [700 MHz]

Information around an intersection is transmitted from a road side equipment (RSE) to vehicles

Theme 2

■ Vehicle-to-Pedestrian (V2P) [700 MHz / cell-phone]

Information of a pedestrian and a vehicle are transmitted between pedestrians and vehicles

Theme 1

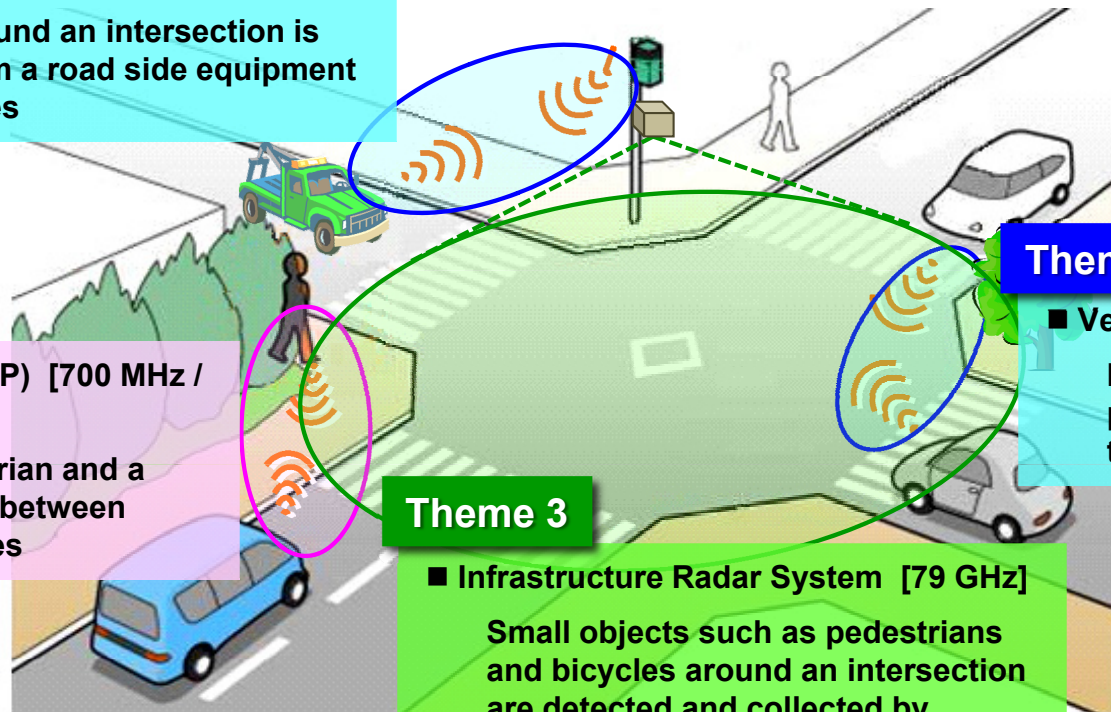
■ Vehicle-to-Vehicle (V2V) [700 MHz]

Information such as speed and position of a vehicle is transmitted to other vehicles

Theme 3

■ Infrastructure Radar System [79 GHz]

Small objects such as pedestrians and bicycles around an intersection are detected and collected by infrastructure radar

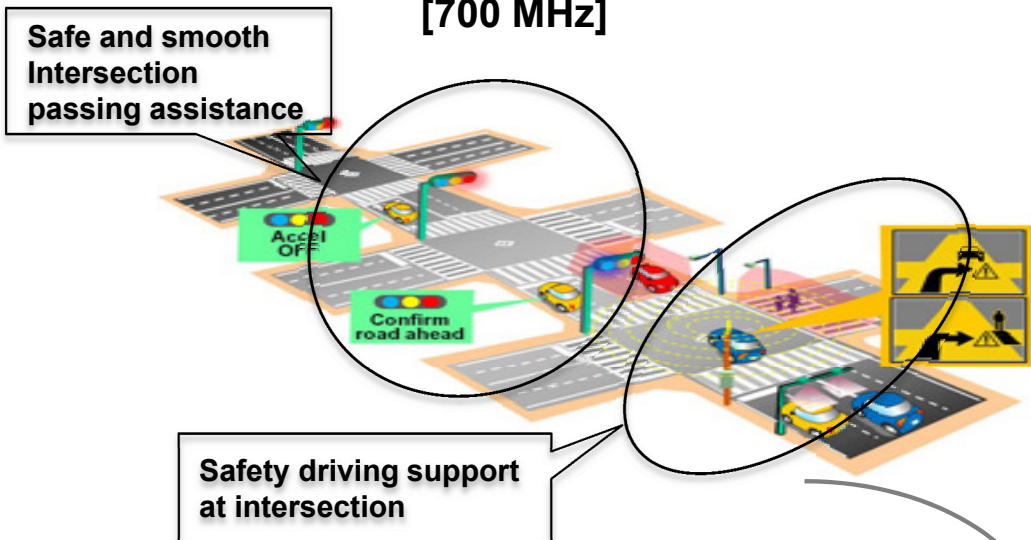


Theme 1: Vehicle-to-Vehicle / Infrastructure Communication (V2I, V2V)

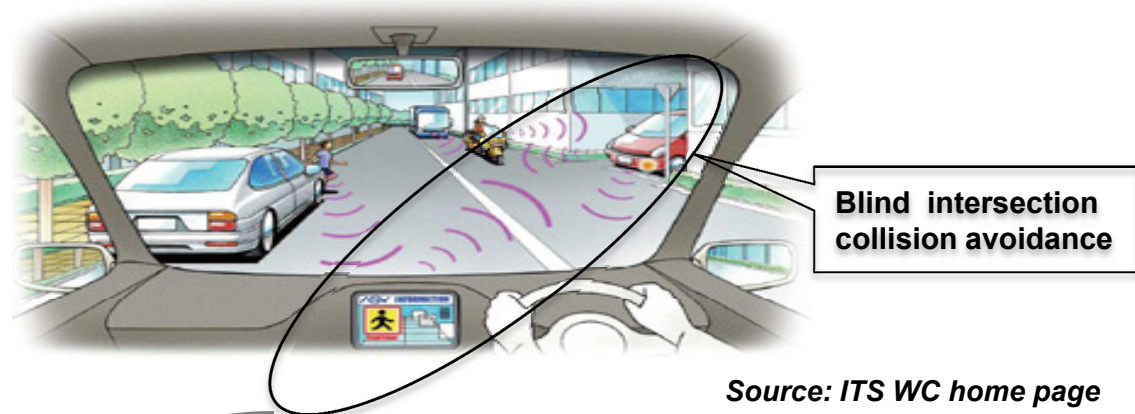
Towards Automated-Driving System using Communication Technology

- V2V / V2I communications contribute the realization of the Cooperative Driving Support system
- Enhanced and sophisticated driving support system are required for Automated-Driving system

Vehicle-to-Infrastructure (V2I) Communication [700 MHz]

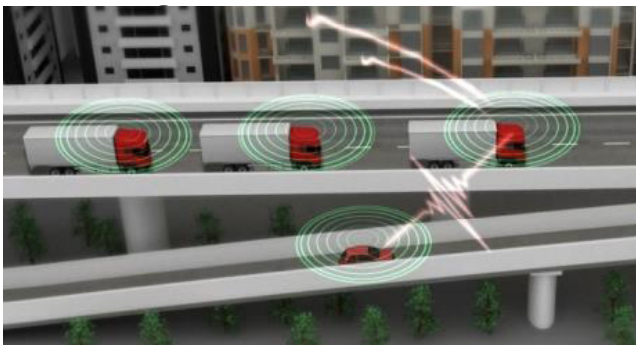


Vehicle-to-Vehicle (V2V) Communication [700 MHz]



Enhanced and Sophisticated

Cooperative Automated-driving



Commercial Vehicle Automatic Driving

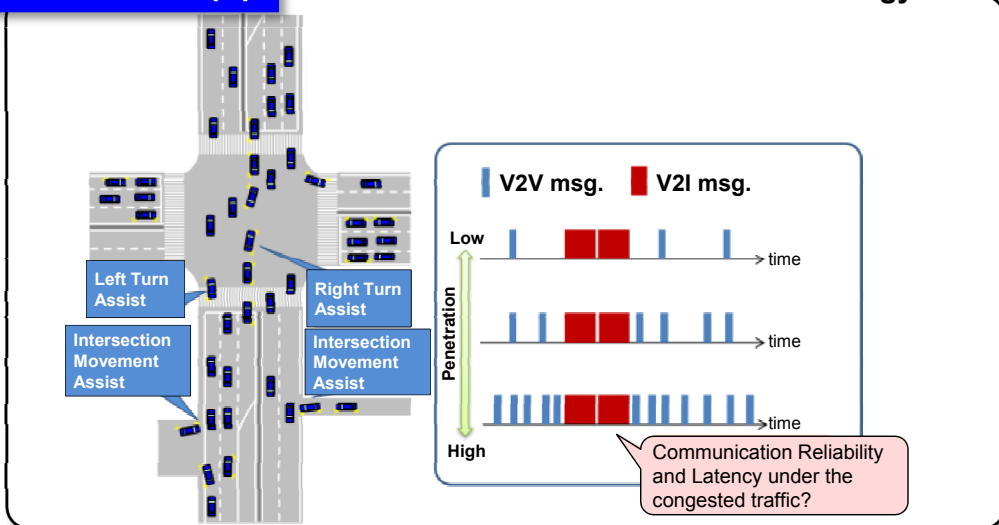


Theme 1: Vehicle-to-Vehicle / Infrastructure Communication (V2I, V2V)

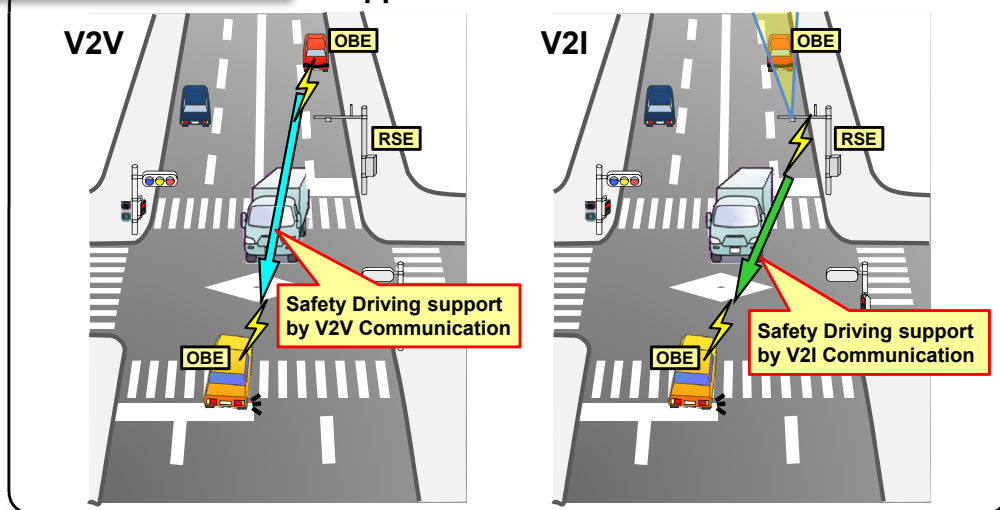
MIC Theme 1

Development of Vehicle-to-Vehicle (V2V) and Vehicle-to-Infrastructure (V2I) communication Technology for Automated-Driving System

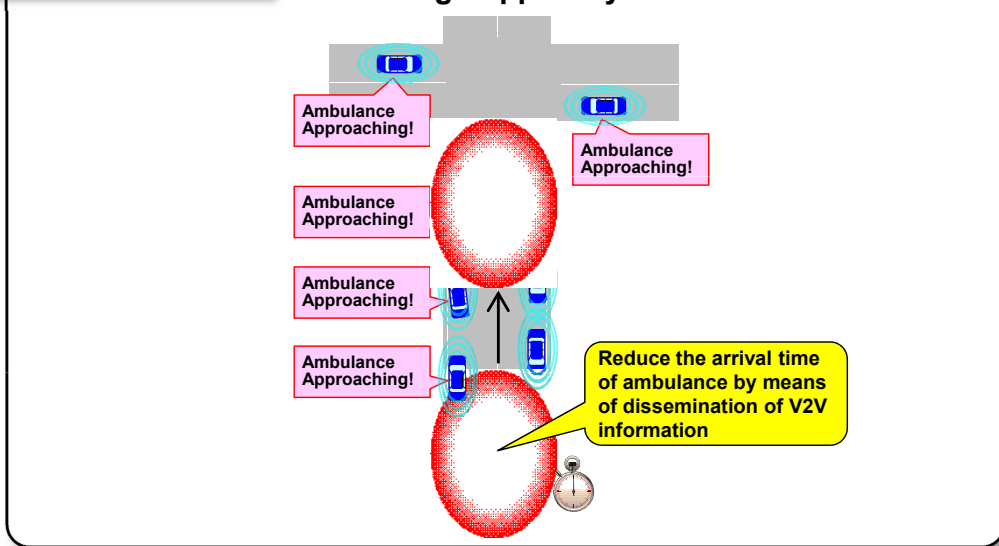
Sub-Theme (a) Research on Communication Technology



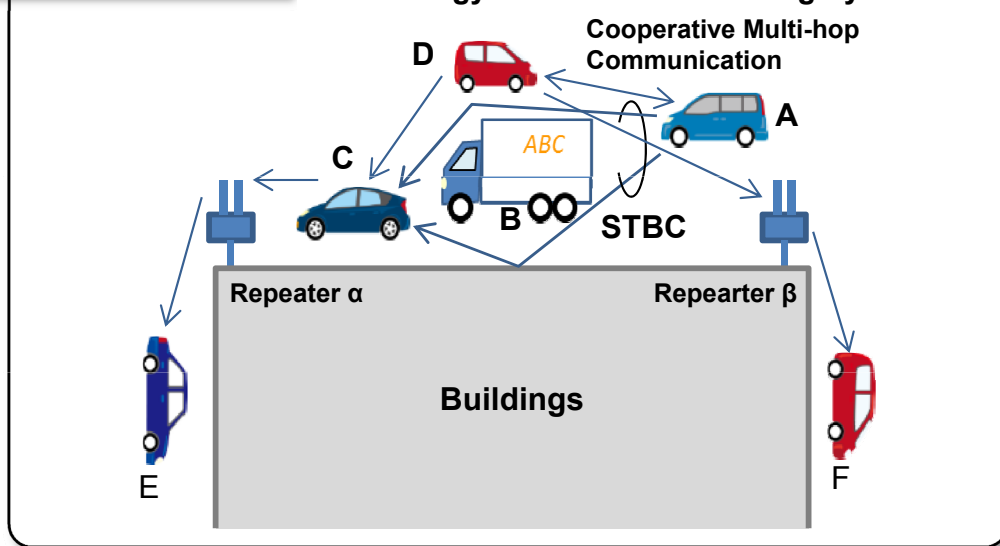
Sub-Theme (b) Research on Cooperative Driving Support Service



Sub-Theme (c) Research on Penetration Promotion of Driving Support System



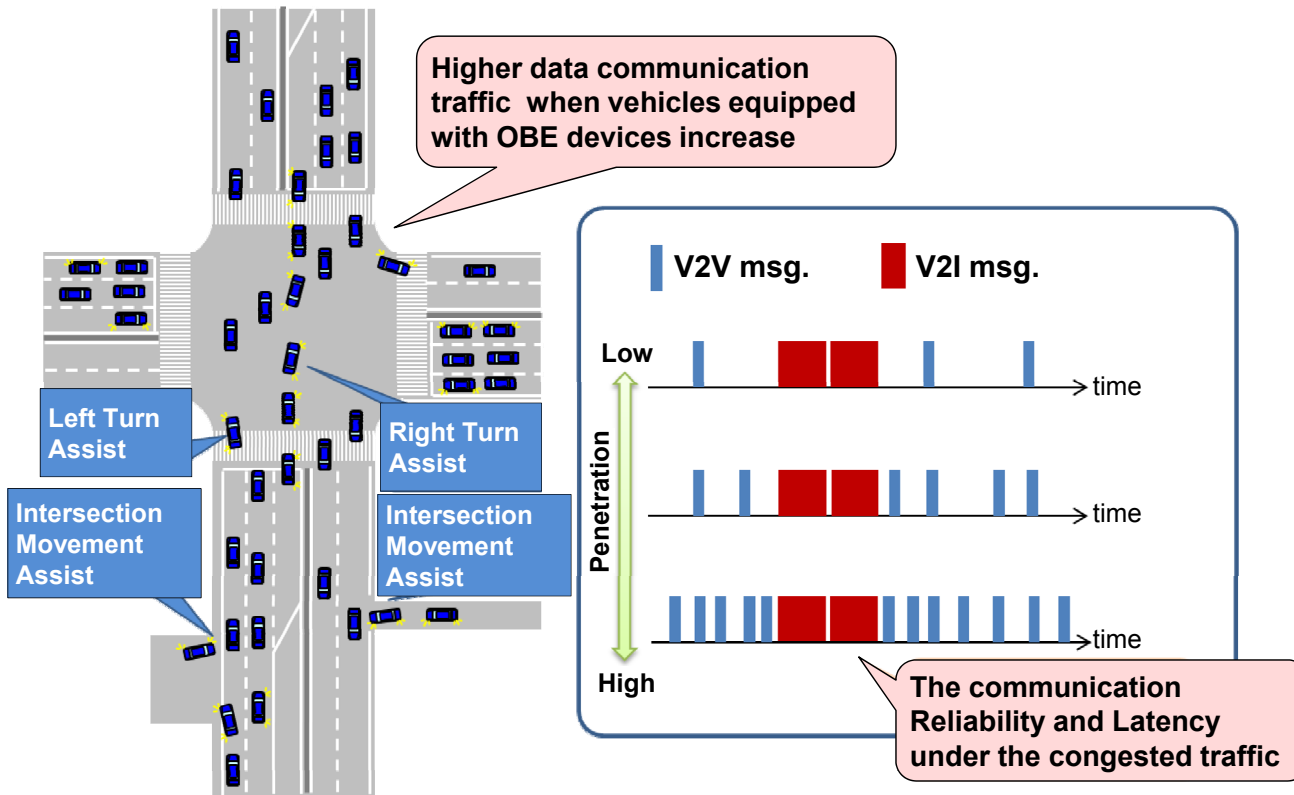
Sub-Theme (d) Research on Reliable and Low-Delay Network Technology for Automated-Driving System



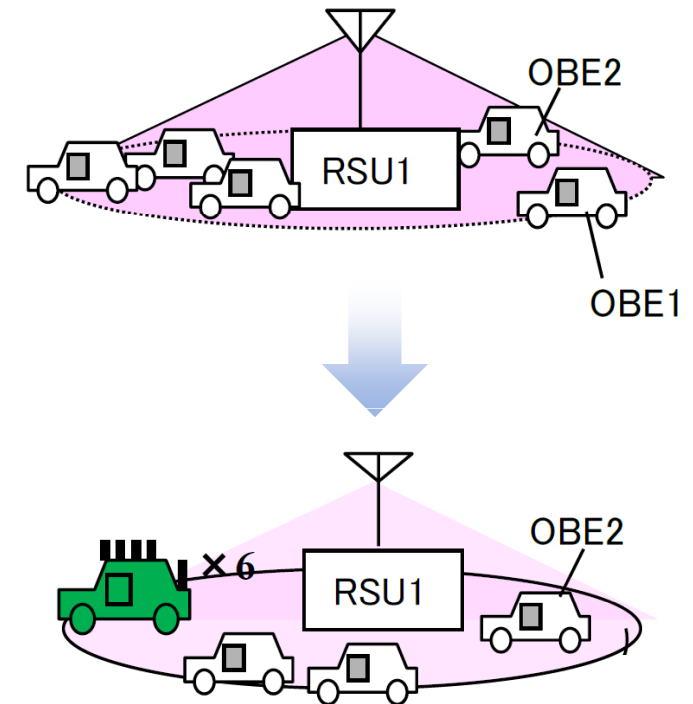
Sub-Theme (a) - Research on Communication technology

Objective

Verify the V2V and V2I communication performance and scalability under the condition that a large number of vehicles exist in the high density



Increase a number of vehicles and measure the packet delivery ratio and transmit delay

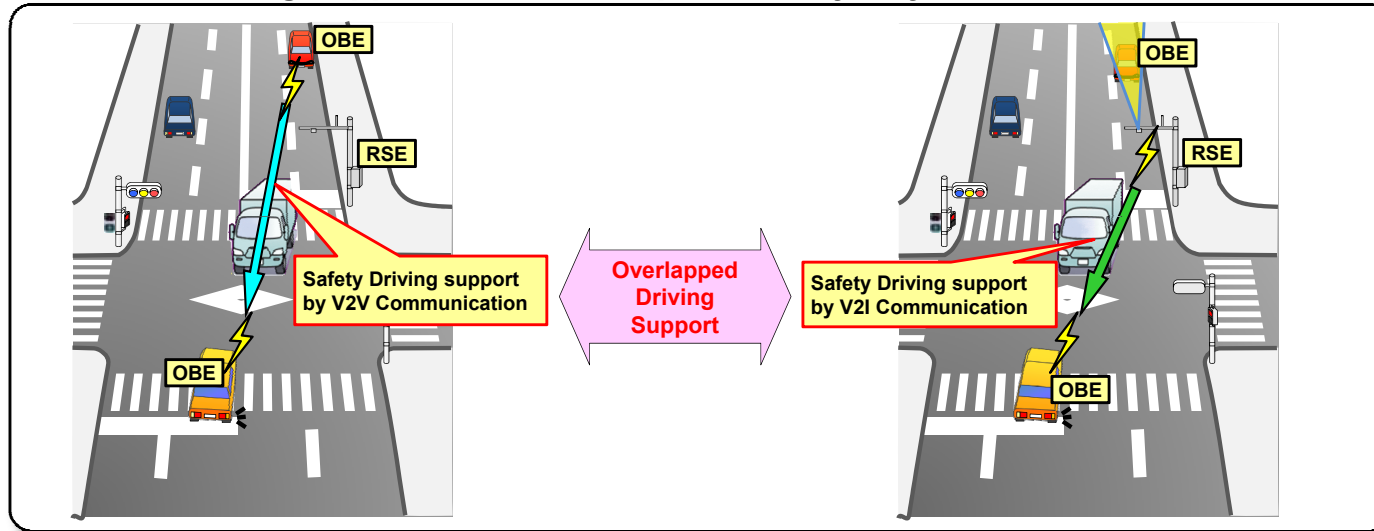


Sub-Theme (b) - Research on Cooperative Driving Support Service

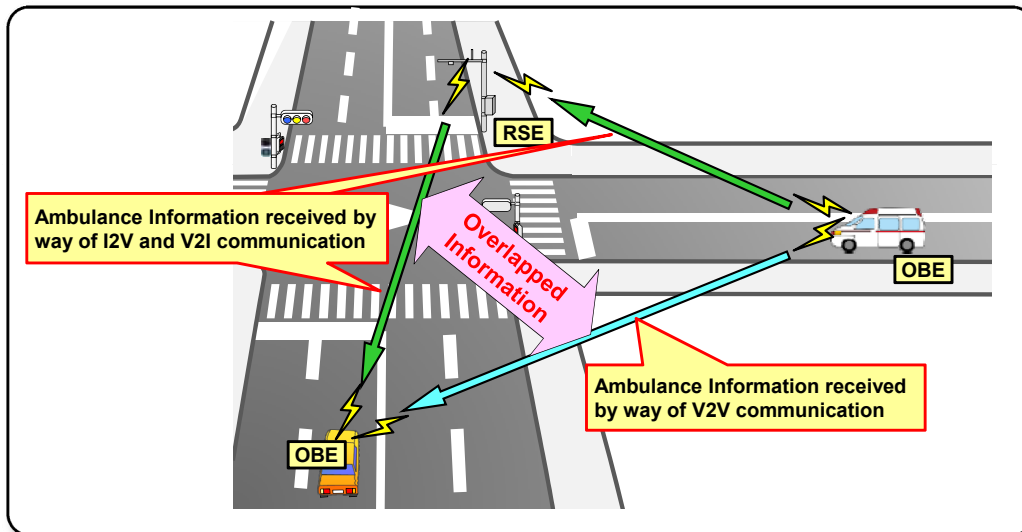
Objective

Examine how to provide drivers with driving support service under the condition that V2V and V2I communications co-exist or plural V2V and V2I services occurs

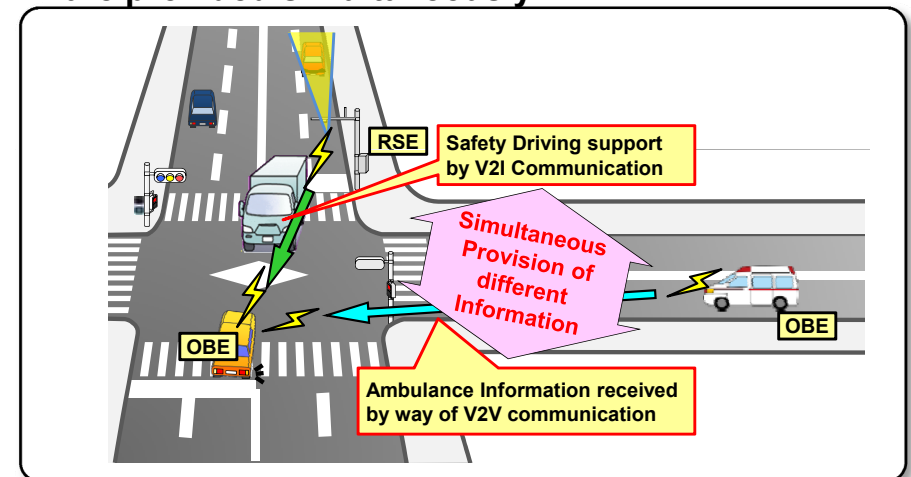
Case: Same Driving support services are provided by way of both V2V and V2I



Case: Ambulance information are provided by way of both V2V and V2I



Case: Driving support service and ambulance information are provided simultaneously

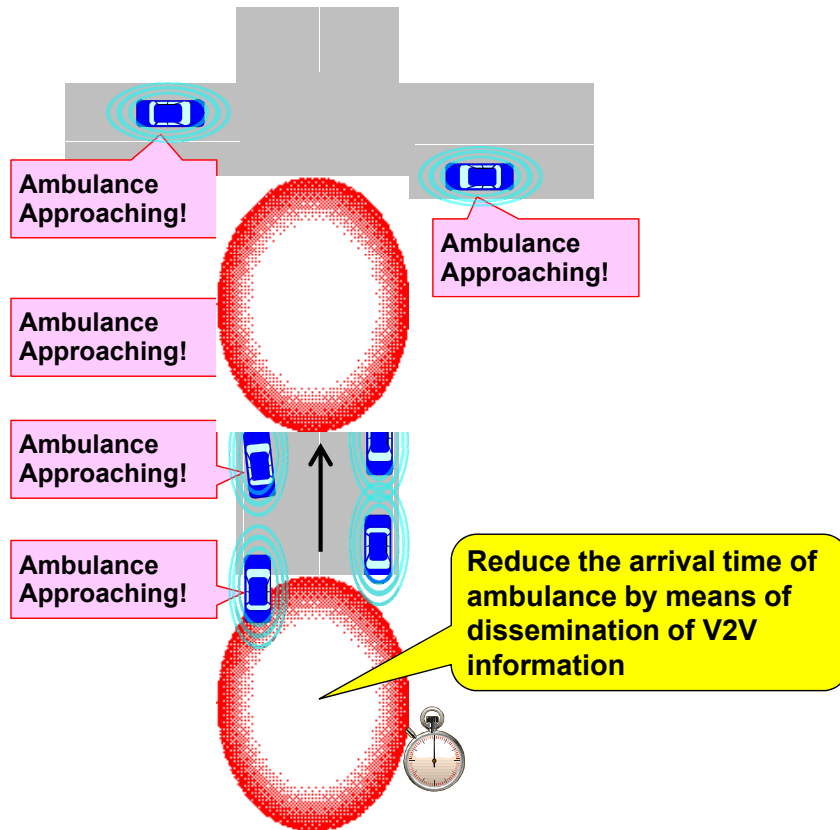


Sub-Theme (c) - Research on Penetration Promotion of Driving Support System

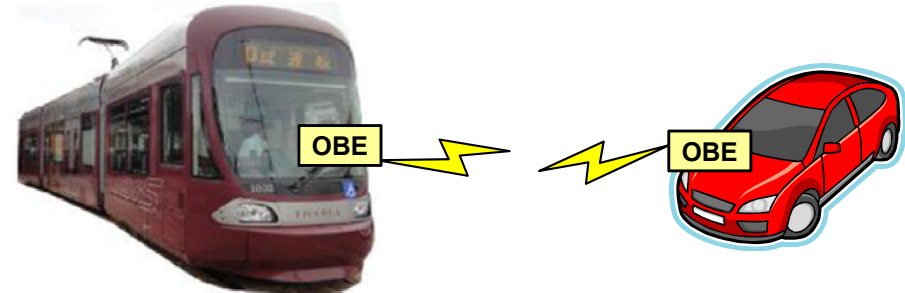
Objective

Examine the effectiveness of V2V communication system when deployed in public vehicles (ambulance, fire truck, tramcar, etc.) for future penetration of V2V system

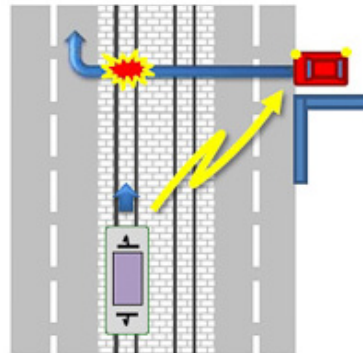
Assistance for emergency vehicle traveling



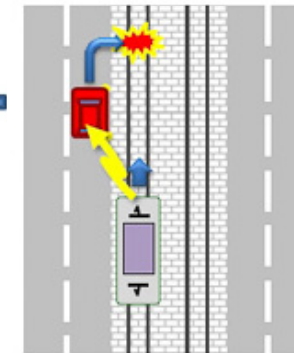
Collision prevention between tramcar and vehicle



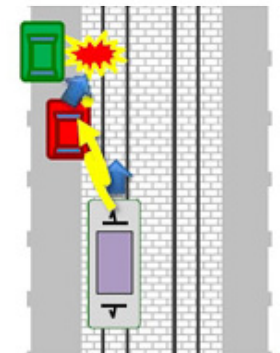
Provision of information at the corner



Provision of information in right turn



Provision of information in overtaking



Source: http://www.hiroden.co.jp/what/new/pdf/130904_press/press_news.pdf

Field Operational Test Area

■ Nagoya



■ Yokosuka



■ Kobe



■ Hiroshima



Roadmap of Research Theme 1

2014

Research of element technologies of V2V and V2I communication

- Verification of communication performance
- Assessment of serviceability of V2V and V2I applications in a controlled environment
- Collecting basic data to analyze the applicability of ambulance traveling assistant

2015

Development of advanced V2V and V2I technology to contribute to the realization of Automated-Driving System

- Large-scaled field operational test with regular drivers in real-world conditions
- Deployment of the system to tramcar, road work vehicle, and other public transportation

2016

2017

2018

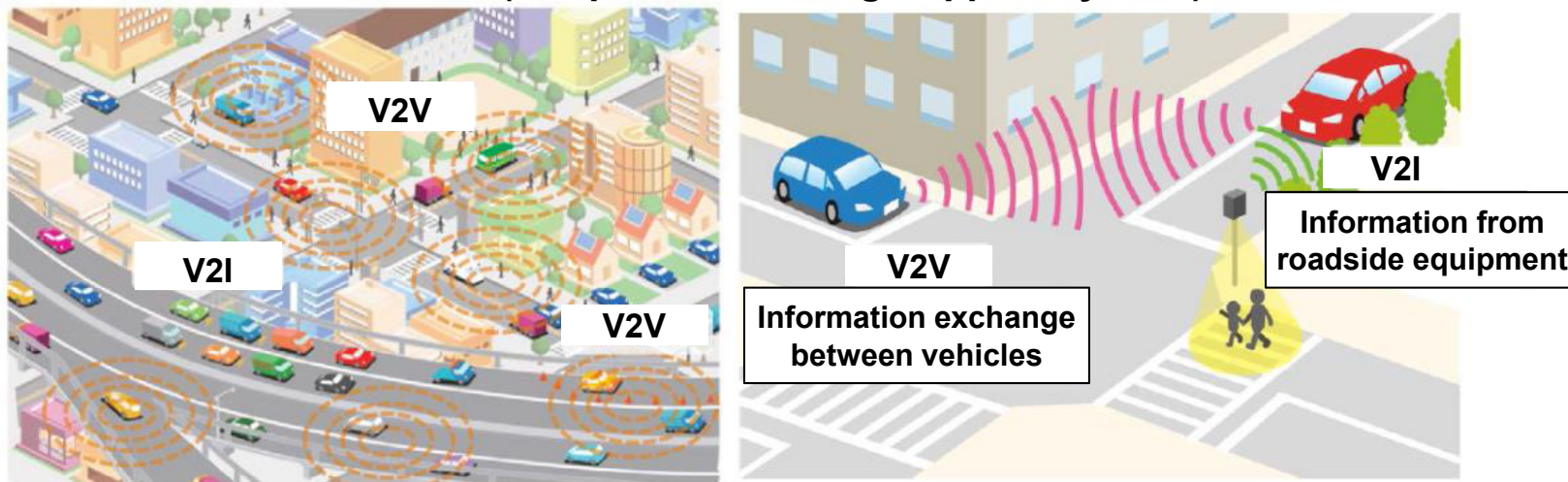
Development for further sophisticated Automated-Driving System and penetration promotion of the system for market expansion

ITS-Connect Promotion Consortium

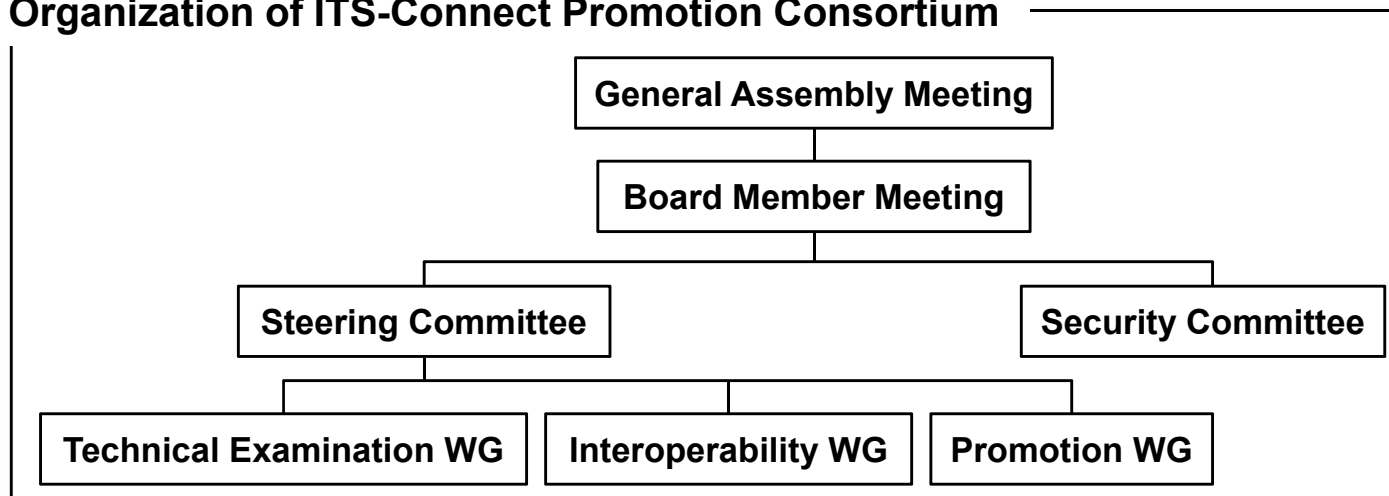
Objective

- Promote R&D and FOT activities of Cooperative Driving Support System utilizing ITS towards the practical use and penetration of the system
- Planning of system operation, management of specification documents, supporting interoperability test, public-relations and promotion of the system

ITS-Connect (Cooperative Driving Support System)



Organization of ITS-Connect Promotion Consortium



• Established on Oct. 28, 2014

• 9 board members



• 2 regular members



Panasonic

Thank you for your attention!