In 2<sup>nd</sup> SIP-adus Workshop on Connected and Automated Driving Systems 2015 Session: Next-Generation Transport (Oct. 28, 2015 11:00-12:30) @ Tokyo International Exchange Center (TIEC)

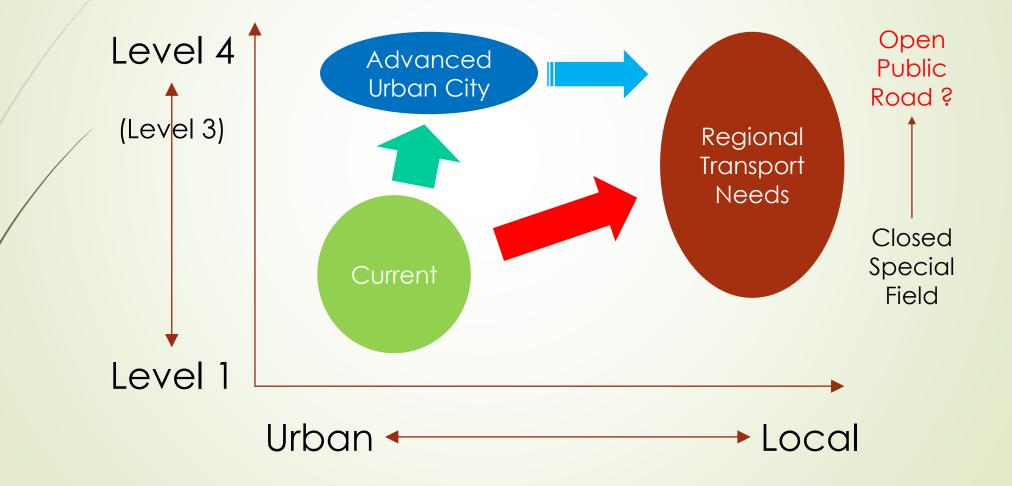
> Next-Generation "Regional" Transport using Automated Driving Technology and Special Ward for Field Practice

> > Takahiro SUZUKI, Dr.-Eng.

Vice Director / Professor,

New Industry Creation Hatchery Center(NICHe), Tohoku University

# How, and Where to be developed automated driving technologies & systems ?



# Tohoku (North-East) Region, Japan

- Distant : "Michinoku" (means "end of road")
- Sparse
- Highly-Age
- Lot of Nature

- ⇒ Smooth & Stress-free
- ⇒ Human-Friendly
- ⇒ Eco-Friendly
- + Great Disaster ...  $\Rightarrow$ 
  - ⇒ Disaster-Resilient

⇒ "advanced problem region" It must be changed into "<u>advanced problem-solving region</u>"

### The Great East Japan Earthquake Disaster on March 11, 2011



[Disaster Investigation by Univ. of Tokyo & Tohoku University]

# Next-Generation Advanced Mobility System ONICHC Research Project in Tohoku University

#### Aobayama Campus Field Experiment

Visualization of campus bus & EV locations
On-demand traffic information system
Auto allocation of shared mobility
Evacuation guidance in emergency
Utilizing EV energies at evacuation place

#### Social Implementation to Tohoku Disaster Area

- Transport System supplementing existing community bus - Multi-mode mobility with evacuation guidance function



### For Social Contribution

Next-Generation Advanced Mobility System Research Group

> Prototype Evaluation Base for Next-Generation Vehicles

Miyagi Reconstruction Park NICHe TAGAJYO BASE

> In the Sony Corporation Sendai Technology Center

Early operation restarting of the suffered companies
 Creation of new industry and employments by advanced technologies

#### Cross-cutting Integration for Advanced Technology Development



- EV Bus - Wireless Charging - In-Wheel Motor - Head-Up Display - Omnidirectional Camera



Micro EV
Autonomous Vehicle
Lithium-ion Capacitor EV
Dual-Mode EV (for emergency)



Driving Simulator
Traffic Simulation
Virtual Space
Driver Sensing

#### Region-based Collaboration of Industry-Academia-Government

- Toyota Motor East Japan, Inc. Outdoor Un-manned Vehicle Next-Generation Distribution
- Kudo Electronics Corporation

Motor, Power Electronics

- Hikichiseiko Co.,Ltd.

Wireless Charging Station

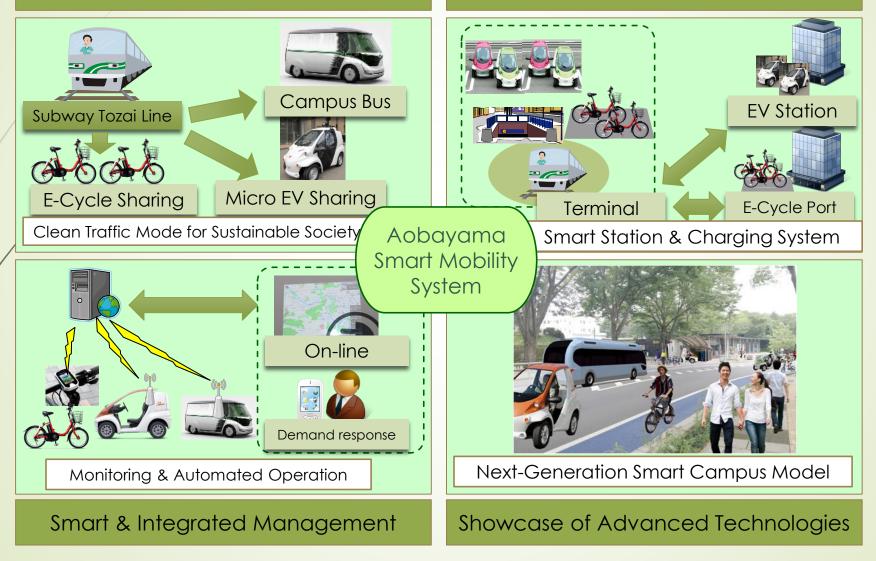
- Murakami Co.,Ltd.

EV Design & Manufacturing under collaboration with Ministries, Prefectures, Cities & Towns

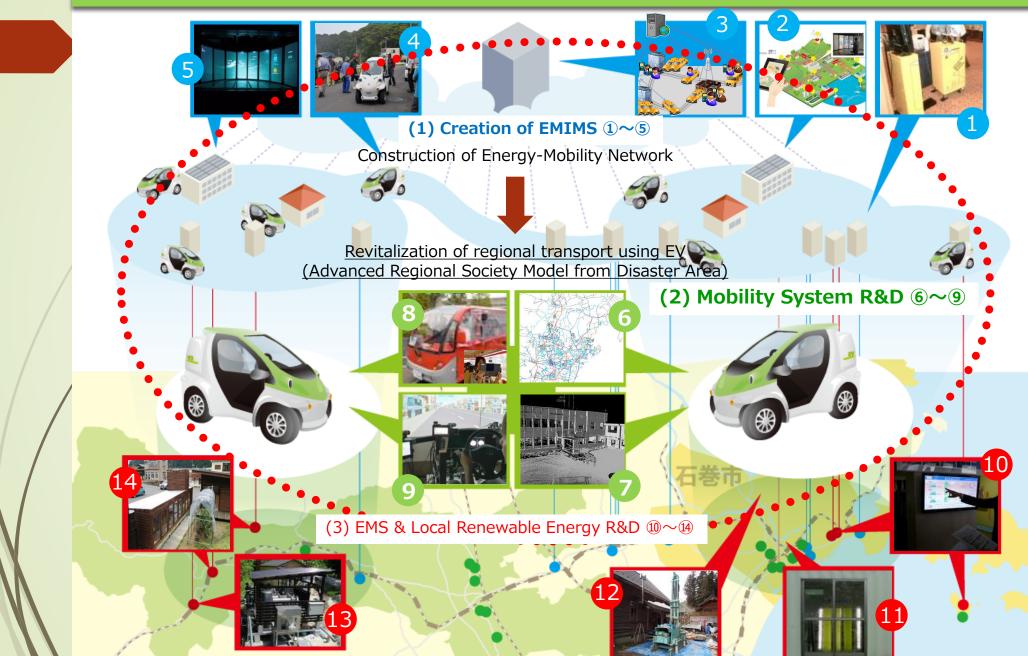
# Aobayama Campus Smart Mobility Vision (Planning)

Smooth Transfer to Multi-Mode

#### **Development of Smart Station/Port**



MEXT Tohoku reconstruction Next-Generation Energy R&D Project (2012-2016) "Creation of Energy-Mobility Integrated Management Systems (EMIMS)"



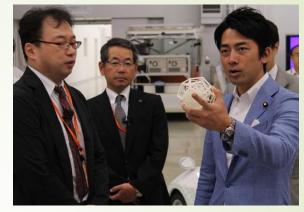
#### Inspections inside and outside of the country to Miyagi Reconstruction Park (Tagajo city)



Shinzo Abe, Prime Minister (Dec. 2013)



T. Nemoto, Minister of Reconstruction Agency (Sep. 2013)



Shinziro Koizumi, Reconstruction Parliamentary Secretary (Aug. 2014)



Sadayuki Sakakibara, Chairman of Keidanren (Jul. 2014)

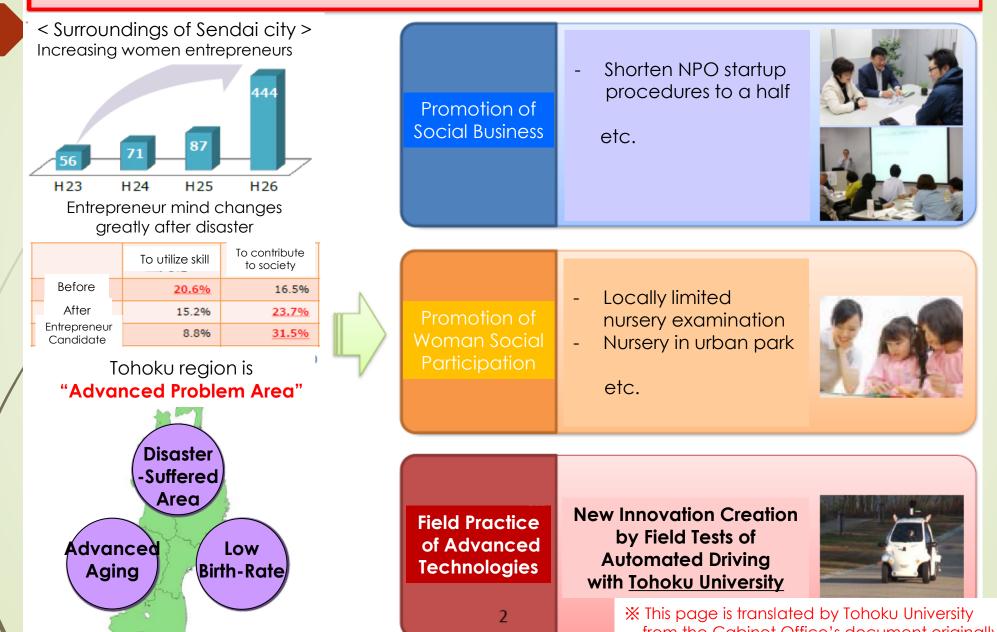


Shoichiro Toyota, President Emeritus of Toyota Motors (Nov. 2014)



Mali Republic (Africa) (May, 2014)

#### Sendai, Miyagi Social Innovation Creation Special Ward - Reformation Base for Promotion of Woman Activities & Social Business -



from the Cabinet Office's document originally in Japanese.

## Advanced Mobility System Practice Field Plan

Advanced Mobility System <u>Practice Field</u> (Open Practice Field / Demonstration Field)

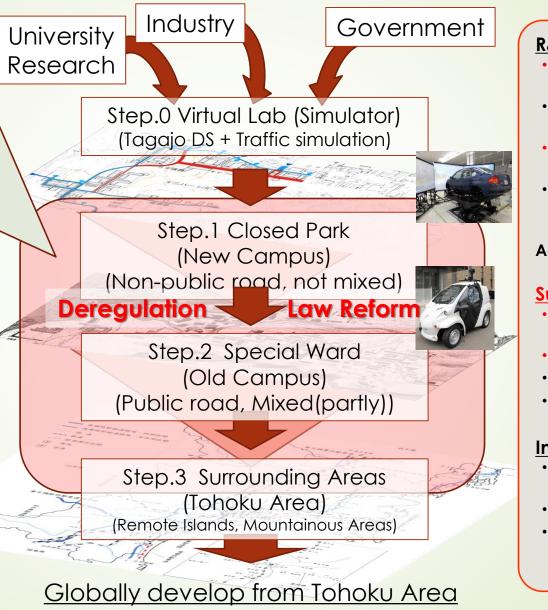
#### For Researcher :

- Hatchery / Nursery / Practice Field
- Utilize Closed Park / Open Road
- Verification of Social Receptivity
- Dissemination to Public
- Advanced Marketing
- R&D considering Practical Needs

#### For Users & General People :

- Attraction of Advanced Technology, Experience of "Near-Future"
- Improvement of Understanding
- Creation of Near-Future Image
- Participation to Near-Future R&D
- Human Resource Creation

Conventional closed R&D Field



#### <u>R&D Support</u>

- Practice Field Operation
   Real & Virtual Proving Ground
- Open Lab (PJ Space) widely open to other sectors
- MICE function (seminars)
   Public Relations
- Global Cooperation Hub Tele-Conference, Travel Support, Accommodation

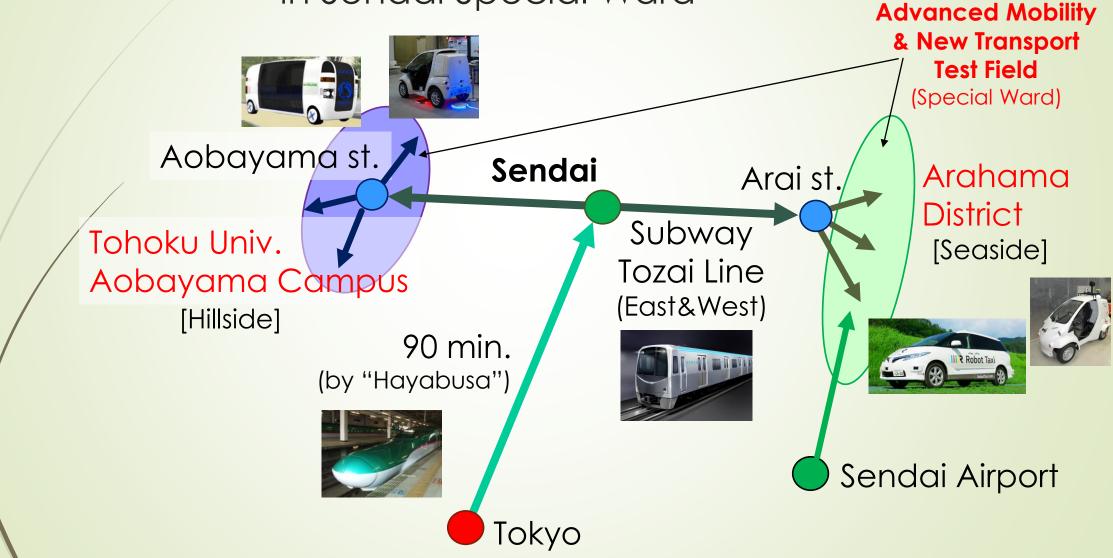
#### **Supporting Dissemination**

- Showcase & Demonstration cooperate w/ top researchers
- Correspondence to Inspection
- Human Resource Development
- Experience Lab

#### **Incubation**

- Support Industry-Academic Collaboration
- Industrialization Support
- · VC

### Vision: Next-Generation Transport Practice Fields in Sendai Special Ward



#### Advanced Technology Field Practice Special Ward : "Creation of Aobayama Campus Next-Generation Advanced Mobility System Practice Field" => Authorized as "Sendai Social Innovation Creation Special Ward" (2015)

Platooning, Remote Drive

Unmanned

Vehicle

#### **Outline**:

Field practice of advanced technologies as automated driving or UAV are executed in Aobayama campus. Utilizing new & existing campus as special ward widely open to active researchers, their realization and deregulation can be quickly proceeded.

UAV(Drone)

Stage 1: Field Practice in New Campus Area

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モ中心とした

Automated

Driving

Stage 0 (Lab): R&D in Academia or Industry (Ex. Miyagi Reconstruction Park) Open to other **R&D** sectors

Stage 3 (Regional Implementation): Model Development to Surrounding Area (Island, Remote Area, etc.)



#### **Contributions**:

Stage 2:

Law Reform Deregulation Wireless Charge

- Quicker realization of technologies
- Active deregulation
- Promotion of field test research
- Attraction of interests
- Dissemination to public
- More attractive campus etc.

Practice Field for Advanced Technologies: "Arahama" District (Tsunami Disaster Hazardous Area in Sendai)

Arahama

**Elementary School** 

(Disaster Remains)

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**Arahama District** 

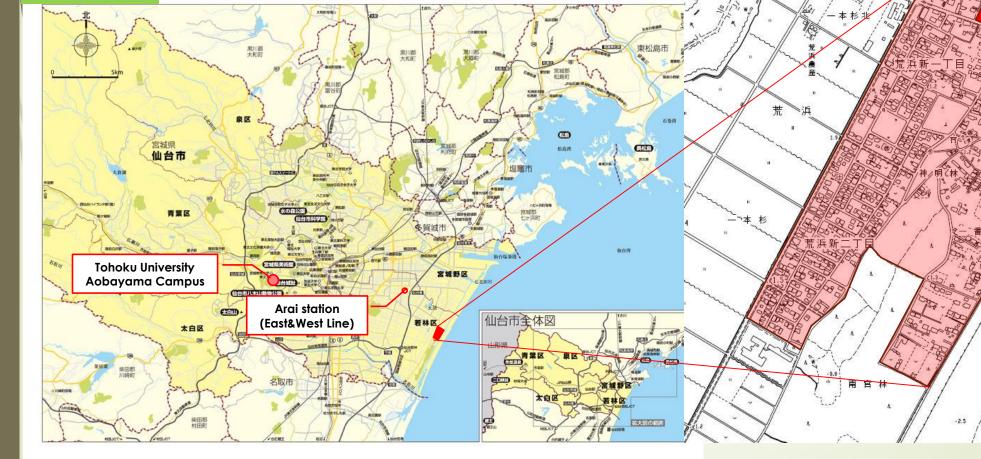
北長沼

松苗畑

/A& // 清掃公社

The residence is restricted in the district. Now constructing to be a practice field for automated driving, drone, and other advanced technologies.

Sendai City Map



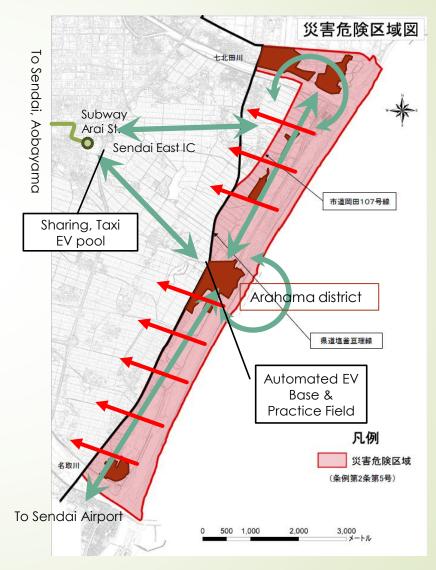




### Arahama District : Field Practice in Disaster Damaged Area for Reconstruction

#### Automated Driving Practice Field Plan

- Reform the coastal disaster-damaged area to a practice field for automated driving to solve problems of regional public transport
- Propose a model of "Last-One-Mile" new mobility
   system and demonstrate field practice
- Area : Arahama district (disaster-damaged area)
- /Future Plan
  - Ordinary : Transport in area and connecting to transport hub
    - (Last one mile, Robot taxi, etc.)
    - => making workable area in the district
  - In Emergency : Smooth evacuation to higher place
- Unmanned inspection, surveillance for evacuee (Utilize autonomous vehicle, drone, etc.)

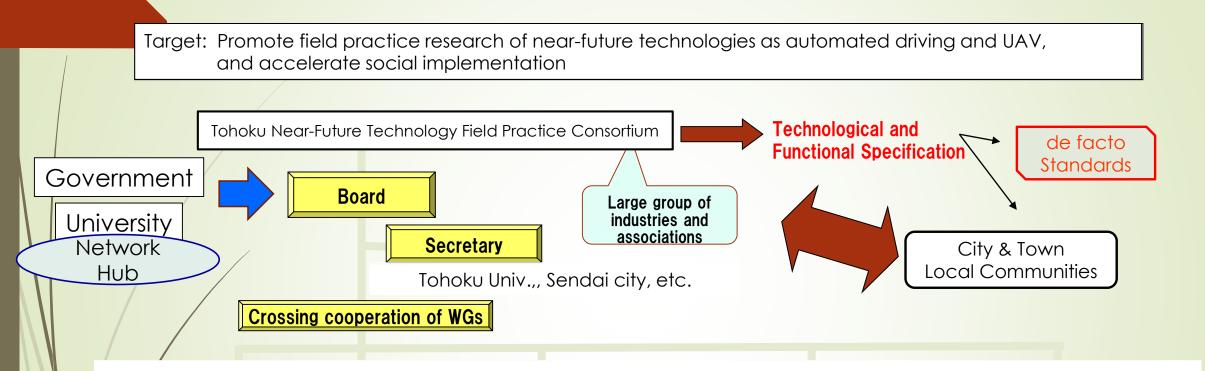


### "Car-sharing" to create "community" (in Ishinomaki)



Japan Car-Sharing Association: http://www.japan-csa.org/

#### "Tohoku Near-Future Technology Field Practice Consortium"



- Workgroups for Automated Driving, UAV, or other technical fields
- Workgroup for legal and social issues (supporting law reformation and deregulation by national government) etc.



# To be "Open Practice Field"

- OEM maker
- Supplier
- Venture
- University
- Local Industry
- Local Government
- Local Academia
- NPO
- Local Residents

# Level 4 $\Leftrightarrow$ Needs for Regional Transport

- Supplier Side (Technological) :
  - Field Experiment for Lv.4 autonomous driving
  - Extraction of the risks on human driving
  - From Simple to Complex
- Demand Side (Social) :
  - Difficulty for Driving by Aged Drivers
  - Decline of Regional Public Transport
- ⇒ How to solve the needs for regional transport by automated driving technology? ... should be: Last-1-mile transport, Dead-man system

← + Highly Adaptive Driving Assistance (for Driver, Environment)

# Thank you for your kind attentions !