European Conference on connected and automated driving



Cross-ministerial Strategic Innovation Promotion Program

SIP Automated driving systems

- Mobility bringing everyone a smile -

April 04.2017 Program Director SEIGO KUZUMAKI

Outline of SIP

Intensive R&D program

- ✓ promote 5-years R&D (FY2014 FY2018)
 ✓ enhancing cross-ministerial cooperation

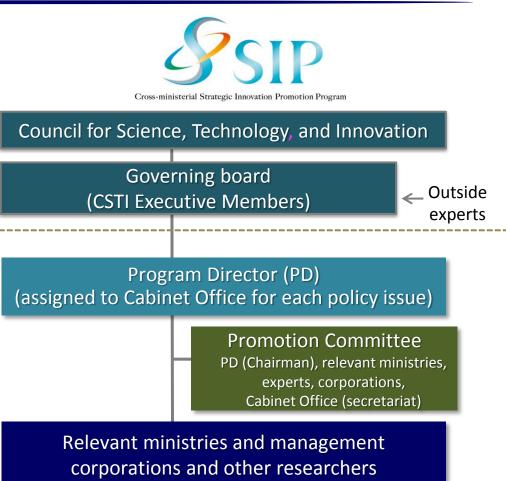
11 research themes

From societal issues such as Energy, Next-Generation Infrastructures and Local Resources, including R&D for AD

Leadership and total Budget **CSTI** appointed Program Directors and allocates the budget for each research theme. *

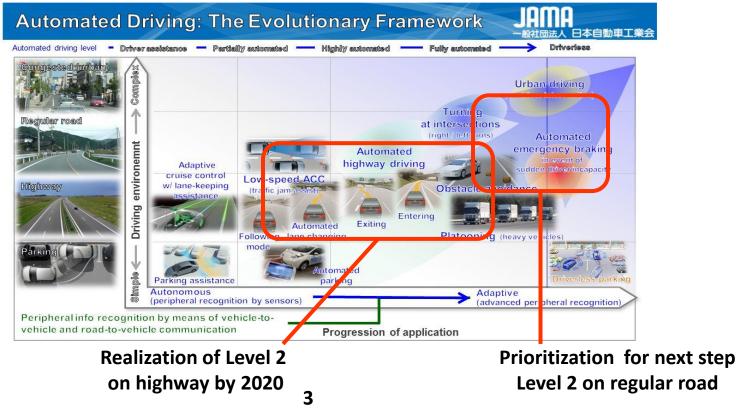
* \50bil in total per year (65% for SIP 11 themes, 35% for medical R&D)

> adus : Automated driving systems for <u>universal</u> <u>service</u>

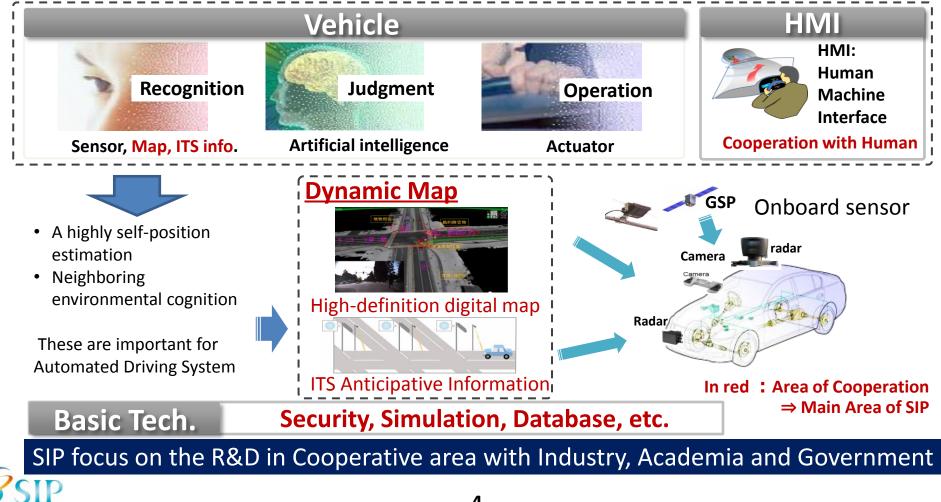


Goal & Exit Strategy

- 1 . Ensuring safety and traffic jam reduction on the road
- 2. Realization and spread of Automated Driving System
- 3. Realization of advanced next generation public bus service for vulnerable people.



Technologies for Automated driving systems

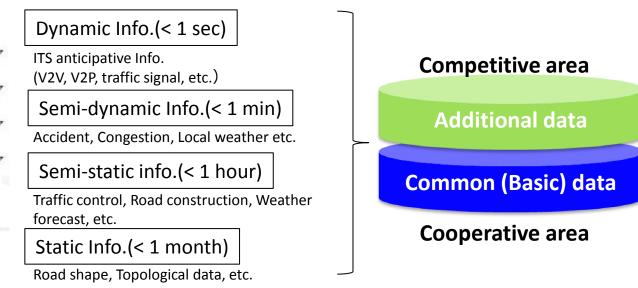


Dynamic map

Use Dynamic Map as an advanced traffic info. database for all vehicles, not only as a precise map for automated driving vehicle.



Base



Dynamic Map Planning Co., Ltd. was established as a result of 2years SIP activity.

Cyber security

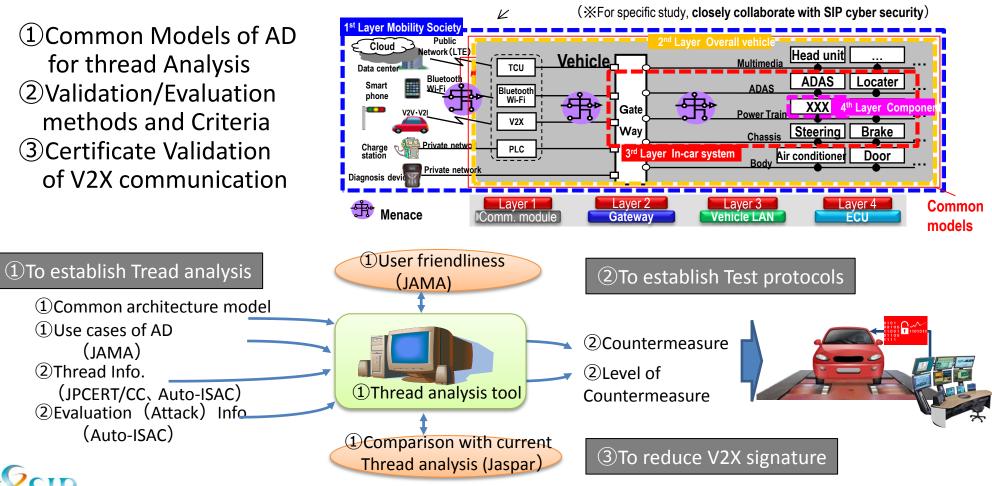
(1)Common Models of AD for thread Analysis ②Validation/Evaluation methods and Criteria (3)Certificate Validation of V2X communication

(1)Use cases of AD

⁽²⁾Thread Info.

(JAMA)

(Auto-ISAC)



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Human Machine Interface

To investigate effects of system information on drivers' behavior.
 To investigate effects of driver state on his/her behavior in transition.
 To investigate effective ways to functionalize AV to be communicative

Driver state

- Cognitively distracted
- Physically distracted
- •Low arousal
- •Lack of SA
- •Out of position



Readiness

- •Head orientation and visual
- performance
- Heart rate and blood pressure
- Body temperature
- •Skin conductance
- •EEG
- Posture and body



Performance at the event

Longitudinal and lateral control of the vehicle
Minimum distance and minimum TTC to the hazard
Time spent to regain control





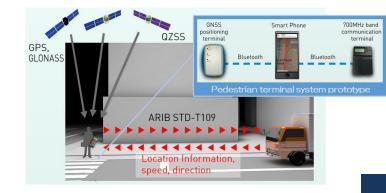
Correlation



Pedestrian accident reduction

Vehicle-to-Pedestrian (V2P) Communication

ITS terminal Control unit



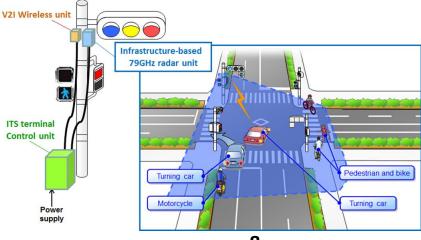
700MHz Direct Wireless Communication

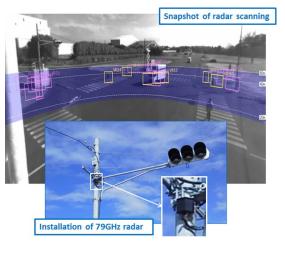
- 700MHz band communication _
- High-precision positioning -
- Danger identification and pedestrian safety support

Infrastructure radar with V2I communication

79GHz band radar from roadside of intersection

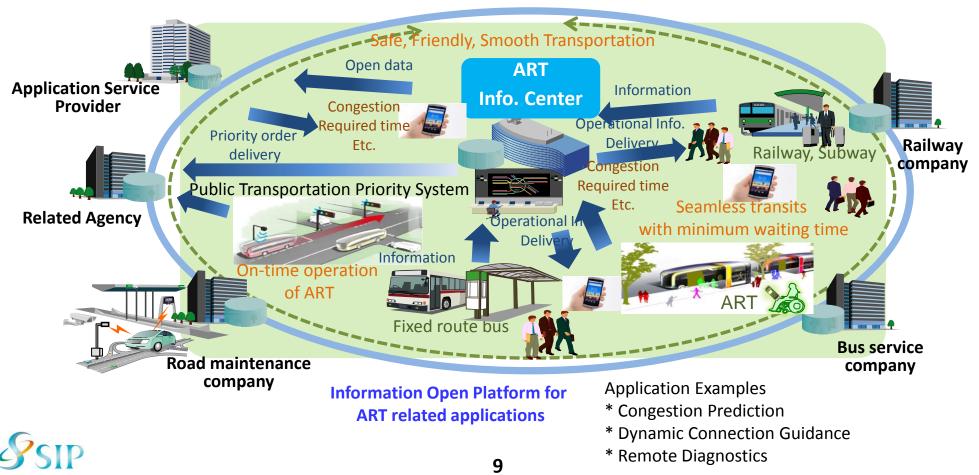
CID





Next generation Transport

ART information center



\ll Purpose \gg

- 1. To activate the R&D
- 2. To prove each elemental technology
- 3. To enhance international cooperation and harmonization
- 4. To Build Social acceptance

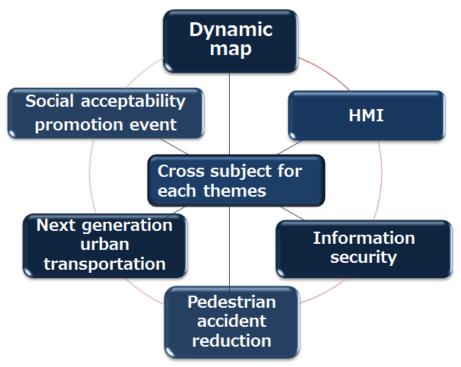
≪Participant≫

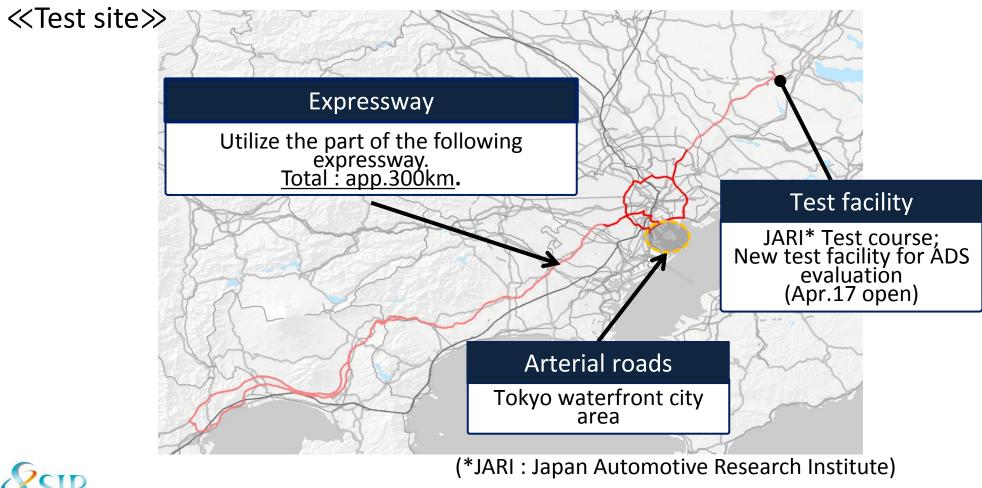
- OEM/Supplier
- University/Research organization
- Ministries, government officers
- Foreign OEM/supplier
- Journalist

\ll Period \gg

Autumn 2017 \sim beginning of 2019

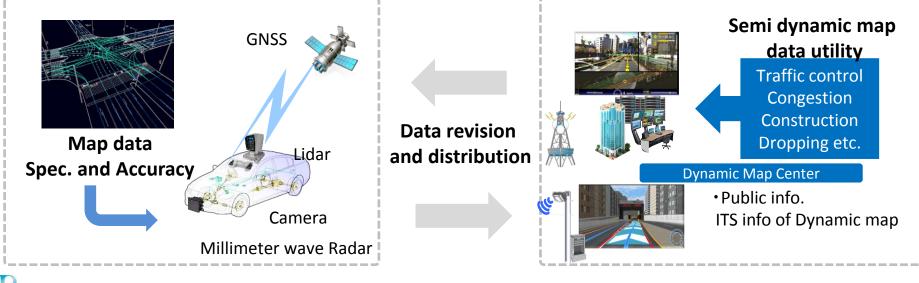
≪Main themes≫





Dynamic Map(Example)

- □ To validate 3D high-resolution digital map data
- $\hfill\square$ To validate data collection and distribution method
- To verify the utility of semi dynamic information
- The map data is provided by SIP-adus.



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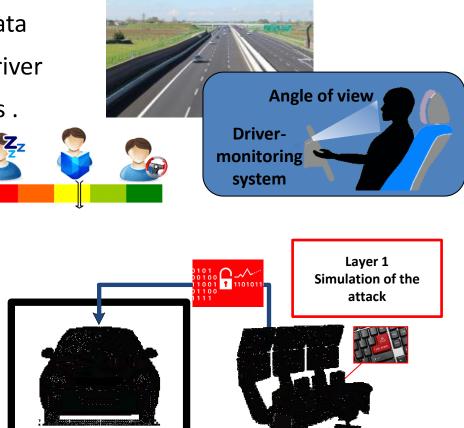
HMI(Example)

- To collect and analyze the driver state data
- To define driving readiness status and driver
- $\hfill\square$ Verification of HMI methods and devices .

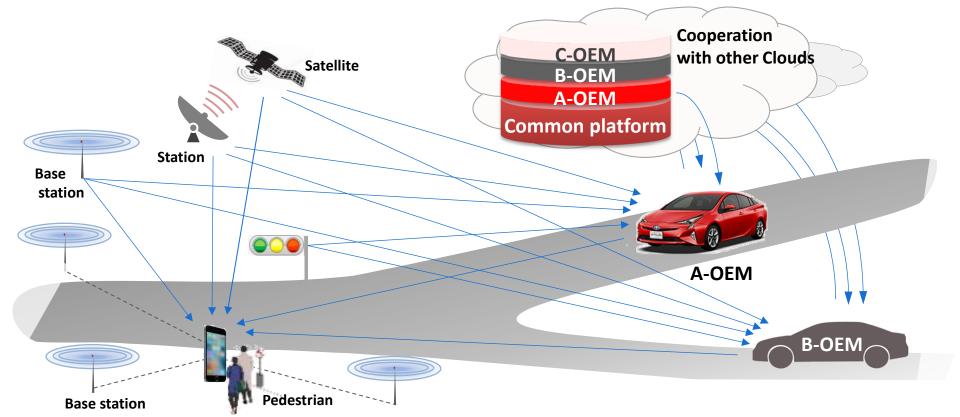


- To Validate the evaluation method
- □ Inspect defense functions of ADV

Layer1: Communication of Out Car Layer2: E/E Architecture Layer3: In Car Bus Protocol Layer4: ECU Software Structure



Common Platform



A common base platform(map, rule etc.) is necessary for keeping safety and the social order. ⇒ Promoting harmonization and standardization



